

AC Servomotors/Linear Motors/Servo Drives

G5 Series

The Preeminent Servo That Revolutionizes Motion Control



>> EtherCAT

»High Speed and High Precision

» International Safety Standards

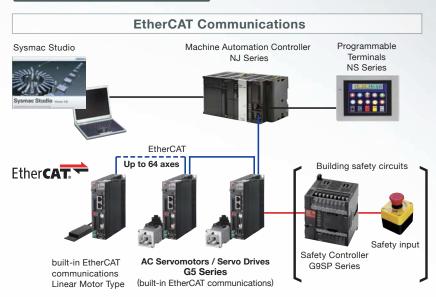


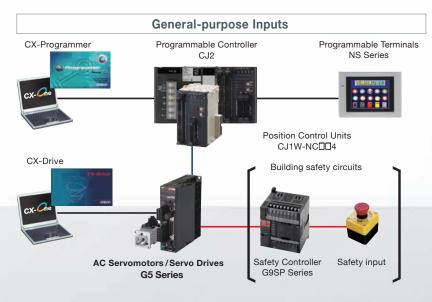
Higher Throughput and Shorter Tact Time, Plus Improved Machine Safety

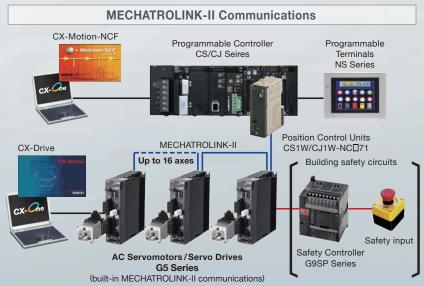


Achieve the fastest position control in the industry by combining the G5 with an OMRON Controller.

System Configuration Example







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EtherCAT® is a registered trademark of Beckhoff Automation

GmbH for their patented technology.

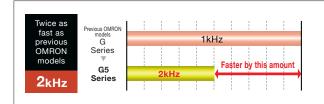
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Industry Top-class Tracking Performance

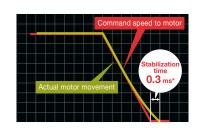
Speed Response Frequency of 2 kHz

Speed response is representative of servo system characteristics. In the G5, the industry's fastest response has been achieved at 2 kHz. By improving the speed response by twice compared to previous OMRON models, the stabilization time has been shortened and this contributes to tact time reduction.



Motion control accurately follows commands.Effective for simultaneous control as well as improving tact time.

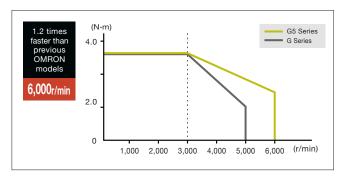
Combination of R88D-KT01L Servo Drive and R88M-K10030L Servomotor. Example of actual measurements taken with gain adjusted by CX-Drive, with inertia ratio of x3 on ball screw mechanical system.



Reduced Tact Time with Higher Speed

Maximum rotation speed: 6,000 r/min*

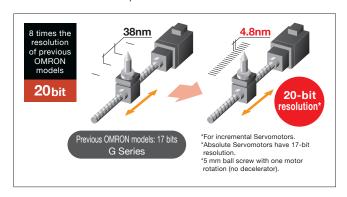
The maximum rotation speed of R88M-series Servomotors has increased to 6,000 r/min, resulting in high-speed positioning that can reduce tact time. *Applicable to 100 V/200 V models with 750 W or less.



Best Positioning Accuracy

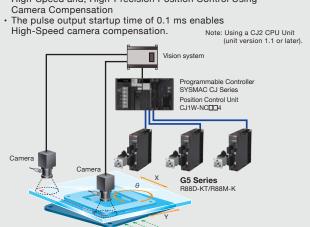
Featuring a 20-bit high-resolution incremental encoder

High-precision positioning can be achieved with the built-in encoder, 8 times the resolution of previous OMRON models at 20 bits.



Example of High-speed/High-precision Application

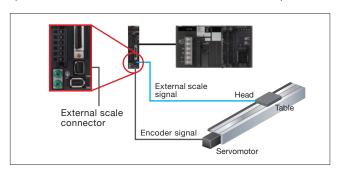
High-Speed and, High-Precision Position Control Using



High-precision Positioning

Fully Closed Loop Control Is a Standard Feature

High-precision and high-response positioning can be realized without being affected by temperature changes by determining the position using direct feedback of the control position from the external scale, to enable using fully closed loop control without options. (The external scale connector terminal is a standard feature.)



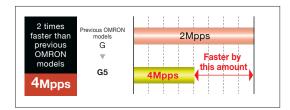
h Accuracy

Safety Motion Control That Provides Safety and Reliability

High-speed and High-precision Positioning

Pulse input response frequency: 4 Mpps

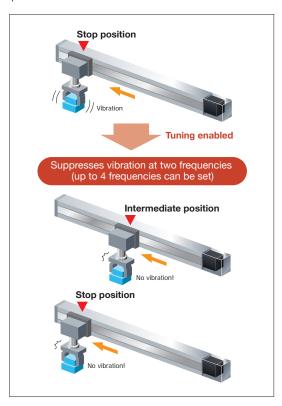
The Servo Drive response to command pulses is 4 Mpps, twice that of previous OMRON models. Response delays are thus reduced enabling high-speed and high-precision positioning.



Ideal for Applications That Require High Accuracy

Improved vibration control function

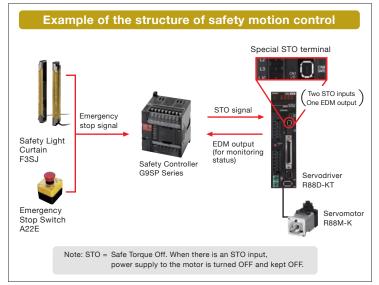
With the vibration control function, if the tip of the device is vibrating, the vibration frequency can be set to remove the vibration. It can also be used to suppress vibration resulting from starting and stopping the device, allowing precise movement.



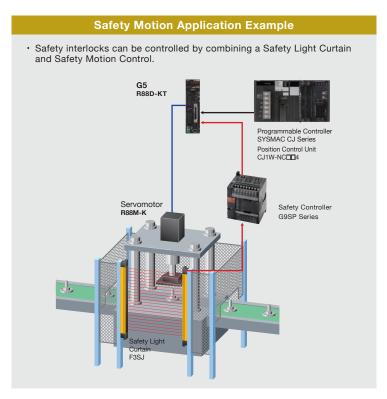
Conforms to the Latest International Standards

Safety and Productivity

The G5 was the first to acquire international standard IEC 61800-5-2 (STO) for motion control in the industry within Japan. It also conforms to the European Directives ISO 13849-1(PLc,d) \ast and EN 61508 (SIL2). Safety control circuits can be constructed with the Servo Drive, delivering both safety and productivity.



* Refer to General Specification of Servo Drive for the compliance of international standards.



Easy Adjustment and Reduce works to

Complete Support from Setup to Maintenance

Software

How to Select Required Support Software for Your Controller

The required Support Software depends on the Controller to connect. Please check the following table when purchasing the Support Software.

ltem	Omron Machine Automation Controller System	Omron PLC System	
Controller	NJ-series	CS, CJ, CP, and other series	
AC Servomotor/Drives	G5-series • EtherCAT Communications (Unit version 2.1 or later reccomended) • EtherCAT Communications Linear Motor	G5-series EtherCAT Communications EtherCAT Communications Linear Motor General-purpose input type(PulseTrain or Analog inputs) MECHATROLINK-II Communications	
	Automation Software Sysmac Studio	FA Integrated Tool Package CX-One	
Software	The Sysmac Studio provides an integrated development environment to set up, program, debug, and maintain NJ-series Controllers and other Machine Automation Controllers, as well as EtherCAT slaves.	The CX-Drive software allows you to set, transfer, and compare Servo Drive parameters, to perform trial operation and adjustments, and to monitor and trace operation. CX-Drive is bundled in CX-One.	
	Setting, adjustment, monitoring/tracing with the Servo Drive can be done via an EtherCAT network. <connecting drive="" method="" servo="" the="" with=""></connecting>	<connecting drive="" method="" servo="" the="" with=""> Direct connection with the Servo Drive. Connection via a PLC (possible with the Servo Drive with </connecting>	
	- Connection via the NJ	built-in EtherCAT communications function)	

Simple Gain Adjustment

Quickly adjust the gain using a wizard.

The autotuning feature provided with the CX-Drive makes it easy to adjust the Servo Drive gain. You can use a wizard to complete gain adjustment in approximately five minutes or less per axis simply by selecting the machine configuration and entering the target set time.

4 steps for gain adjusted (5 minutes per axis)

Autotuning

1. Machine Configuration

Although previously the machine configuration was set using parameters, it can now be selected from ball screws, turntables, belts, and other devices.

2. Automatic Adjustment

Setting for automatic adjustment and conditions after completing automatic adjustment.

3. Autotuning

Implement auto-tuning until reaching to a target value. Stabilization time, overshooting amount and efective load rate can be monitored.

4. Autotuning Completed

After completing autotuning, the results can be checked using the data tracing.

Editing Parameters

- Operation is as easy as with a digital operator.
- Easily set parameters for Inverters and Servo Drives.





Setting screen image Sysmac Studio CX-Drive

Simple FFT

- Device frequency characteristics can be easily measured to analyze resonant frequencies.
- Use notch filters for resonance frequencies to improve response.

 Sysmac Studio CX-Drive









Automatic damping control setting

Settings for damping control for the axis at the tip of the machine in a short time

Automatic damping control setting function is useful to execute damping control for Servo Drives. Manual settings will not be necessary. JOG operation, measuring vibration and parameter settings can be made on one screen.

2 steps for damping filter settings (5 minutes per axis)

Starting automatic damping control setting

1. Measuring machine vibration

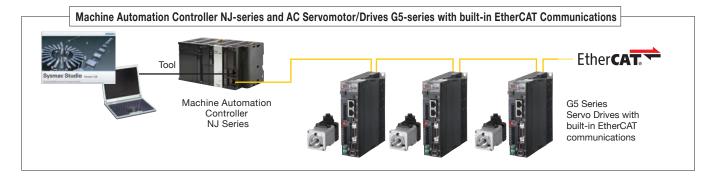
Automatically measures vibration frequency by starting JOG operation from the software or operation executed by the Controller.

2. Damping filter setting

Apply the damping filter 1 to 4 for the measured vibration frequency. Vibration can be suppressed by setting the filters.

Damping control filter setting completed

Sysmac Studio CX-Drive Starting automatic setting function JOG operation Measuring vibration/ Settings Measuring vibration/ Settings Measuring vibration/ Settings Measuring vibration/ Settings

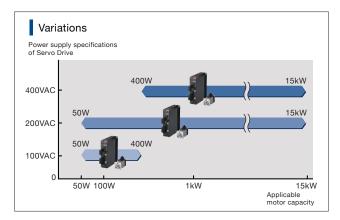


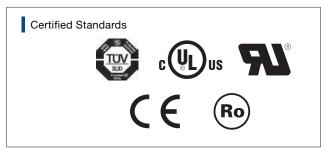
Easy Adjustment and Reduce works to System Start-up

Globalization

Lineup of 400VAC Servomotors

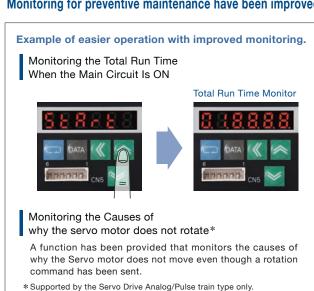
Servomotors are available for 100VAC, 200VAC, and 400VAC. And they conform to international safety standards for easy application anywhere worldwide.





Reduced Work with Increased Monitor Functions

Monitoring for preventive maintenance have been improved.

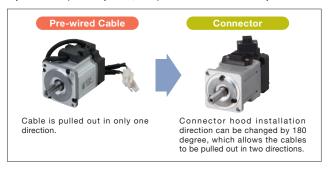


Flexible cable pull-out direction

Direct conenctors for power cable, encoder cable, and brake cable connection.

In case that user creates motor cables, cable pull-out direction can be changed by 180 degree. (Refer to G5 Series User's manual (Cat,No. I571/I572) for the information about applicable motor capacity and connection method).

If you use cables provided by Omron, cable pull-out direction is limited to only one direction.



Side by side installation to save space

Possible to install multiple drivers side by side.



*Drivers with 750W or less capacity only

There are usage limitations including ambient temperature and load rate. Refer to G5 Series User's manual (Cat.No. I571/I572) for detailed information

Servomotors Conform to IP67

(Excluding Through-shaft Parts)

The power cable and encoder cable also conform to IP67

*Applicable to 3 to 20m cables of 100V/200V models with 750W or less.

The Servomotor provides IP67 protection, enhancing resistance to the environment.



Reduced Stabilization Time by Suppressing Vibration

60% cogging torque reduction (compared to previous G models)

Motor torque variation is reduced due to a 60% reduction in the cogging torque, resulting in high-precision positioning. This enables smooth operation at low speeds.

Lineup of Linear Motors to Achieve Higher Speed and Higher Precision

Inherited functions and performance of G5 series with EtherCAT communications

EtherCAT

Linear motors joined the lineup and the following functions of G5 series achieve higher speed and higher precision.

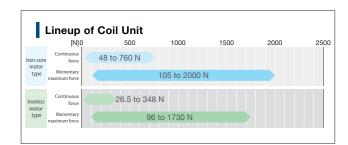
- * High-speed communication via EtherCAT communications at 100 Mbps
- * Autotuning for simple adjustment
- * Useful damping control function to improve device quality
- * Safety function STO (Safe Torque Off)



Selectable motors suitable for device

Iron-core motor type and ironless motor type

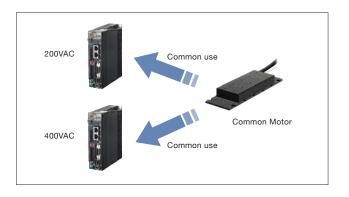
You can choose between compact and high-thrust iron-core motor type and cogging-free ironless motor type with excellent speed stability



Power supply voltage sharing iron-core motor

Using the same Iron-core motor for 200VAC/400VAC

Iron-core motor type The same motor can be used for 200VAC and 400VAC. The same maintenance parts for motors can be used regardless of device and user.



Reduced tact time with higher speed

Higher speed by direct drive

Significantly higher speed than ball screws contributes to make G5 series suitable for faster device application and reduce tact time.

Maximum speed 16 m/s*

* This value is for R88L-EC-GW0309 200VAC motor. It is limited by power supply voltage, model, linear guide, linear scale, and load.

High-precision positioning

Available with various linear scales

High-precision and high-speed positioning Maximum speed at 0.01 μm of scale resolution for serial communications: 4 m/s*

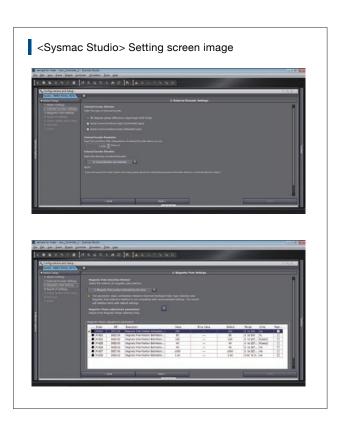
* This value is for Servo Drive. It is limited by the scale specifications. Available linear scale

Serial communications (incremental/absolute), phase A/B/Z pulse type

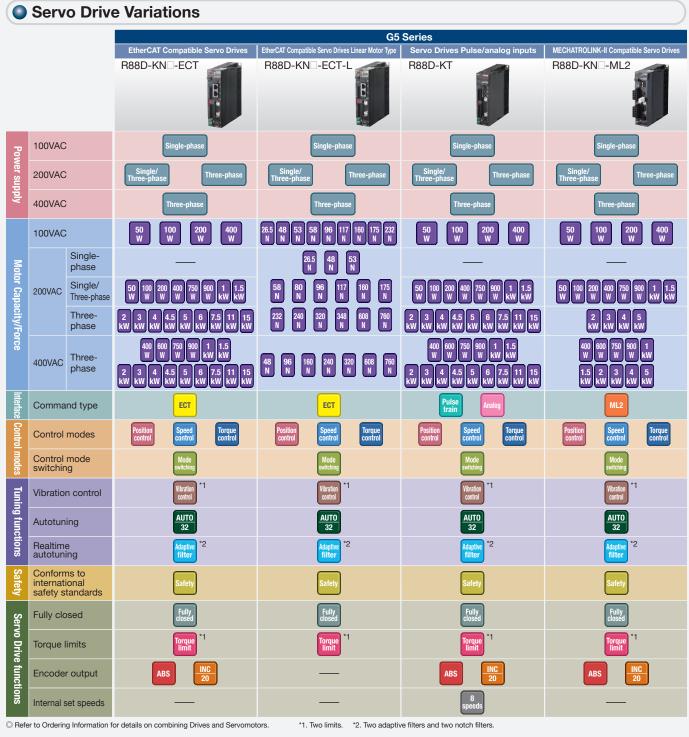
Quick setup

Automatic setup

Automatic setup for motor parameters by selecting the motor. A wizard helps set the scale direction, magnetic pole, or current gain automatically.



The optimum combination can be found from a v model variations to handle various applications.



Functions

ECT: EtherCAT high-speed Servo communications motion network.

Position control: Control is applied to move to the target position and then stop at the target position.

Vibration control function: Vibration is suppressed by automatically setting a filter for the vibration frequency.

Adaptive filter: The machine load inertia is calculated in realtime and the result is used to automatically set the

Internal set speeds: Speed control according to the internal set speed that is set for the parameter.
Up to 8 internal set speeds can be selected.



Pulse train: The speed and travel distance are input to the Servo as pulse

Speed control: Control is applied to change the linear or rotational speed. For example, speed control is used for applications such as turning grindstones, controlling welding speeds, and controlling feeding speeds.

> Autotuning: This function automatically sets an appropriate gain based on the rigidity setting of the machine load; 32 levels of rigidity settings are possible.

Safety function: Conforms to IEC 61800-5-2 (STO), EN ISO 13849-1: 2008 (PLc,d), ISO13849-1: 2006(PLc,d) and EN 61508 (SIL2). **Analog:** The speed and torque are input to the Servo as analog signals

Torque control: Control is applied to adjust the rotational force. Torque control is suitable for applications such as parts insertion, pressing, and screw tightening.

Absolute output: When the Controller power supply is turned ON, the Controller reads the Servo absolute position data to restore the absolute position.

Fully closed (fully closed loop control): Positioning using direct feedback of the current position from the external scale.

ML2: MECHATROLINK-II high-speed

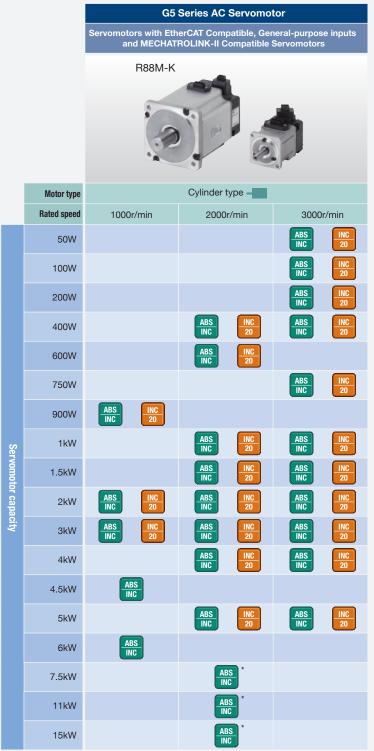
Command control mode switching: Switching is possible between any two of the three control modes: position control, speed control, and torque control.

Incremental output: When the controller power supply is turned ON, operation is always started from the origin. A 20-bit resolution is provided on models with incremental outputs.

Torque limit: Switching is possible between the first torque limit and the second torque limit to limit the Servomotor output torque.

ariety of functions and

Motor Variations



		G5 Series Linear Motor				
		Servomotors with Et Linear me				
		R88L-EC-FW-	R88L-EC-GW-			
			A series			
	Motor type	Iron-core	Ironless			
	26.5N		Iron			
	48N	Iron				
	53N		Iron			
	58N		Iron less			
	80N		Iron			
	96N	Iron				
	117N		Iron			
Le	160N	Iron				
near Mo	175N		Iron less			
Lenear Motor Force	232N		Iron less			
.e	240N	Iron				
	320N	Iron				
	348N		Iron less			
	608N	Iron				
	760N	Iron				

* The rated speed is 1,500 r/min

Functions

absolute/Incremental output: The Servomotor can be switched between an absolute output and an Incremental output. When an absolute output is selected and the Controller power supply is turned ON, the Controller reads the Servo absolute position data to restore the absolute position. A-17bit resolution is provided on model with an absolute output and an incremental output.

Iron-core: Coil units consist of cores and coils. Compact and high-thrust type.

Incremental output: When the controller power supply is turned ON, operation is always started from the origin. A 20-bit resolution is provided on models with incremental outputs.

Iron less: Coil units do not include a core. Cogging-free type with excellent speed stability.

R88M-K/R88D-KN -ECT

System Configuration





Machine Automation Controller NJ Series

Automation Software

Sysmac Studio



EtherCAT Cables

Use a category 5 or higher cable with double, aluminium tape and braided shielding.



Support Software

 CX-One FA Integrated Tool Package (Including CX-Programmer)

Support Software

 CX-One FA Integrated Tool Package (Including CX-Drive)



High-Speed and High-Precision G5 Series EtherCAT Communications with the Controller

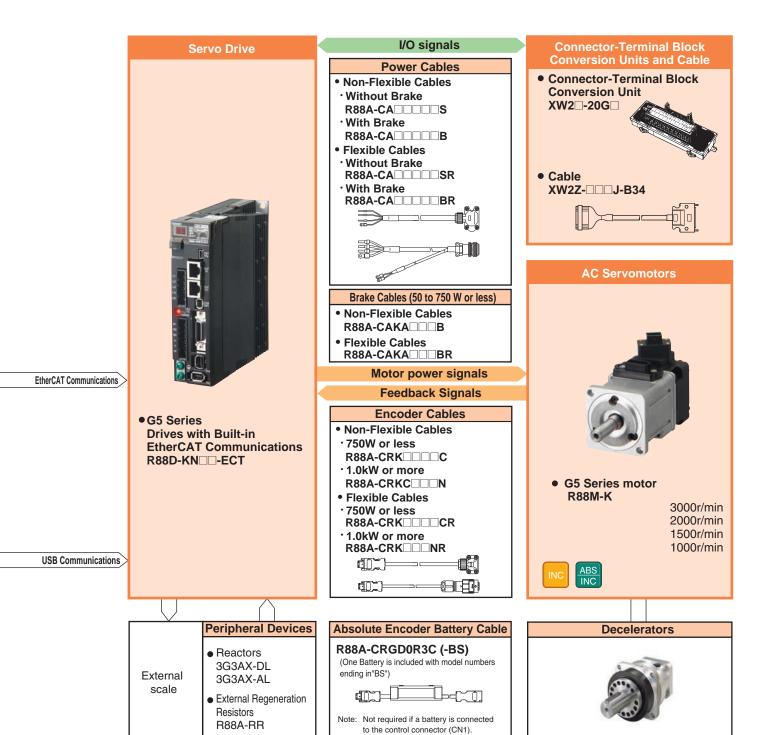




- High-accuracy positioning with fully-closed control.
- Servo Drives for 400VAC globally widens applicable systems and environment, including large-scale equipment.
- Safe design and Safe Torque Off (STO) function.
- Vibration can be suppressed in acceleration/deceleration even in low-rigidity mechanical systems.







R88L-EC/R88D-KN -ECT-L

System Configuration





Machine Automation Controller NJ Series

Automation Software

Sysmac Studio



EtherCAT Cables

Use a category 5 or higher cable with double, aluminium tape and braided shielding.



Support Software

 CX-One FA Integrated Tool Package (Including CX-Programmer)

Support Software

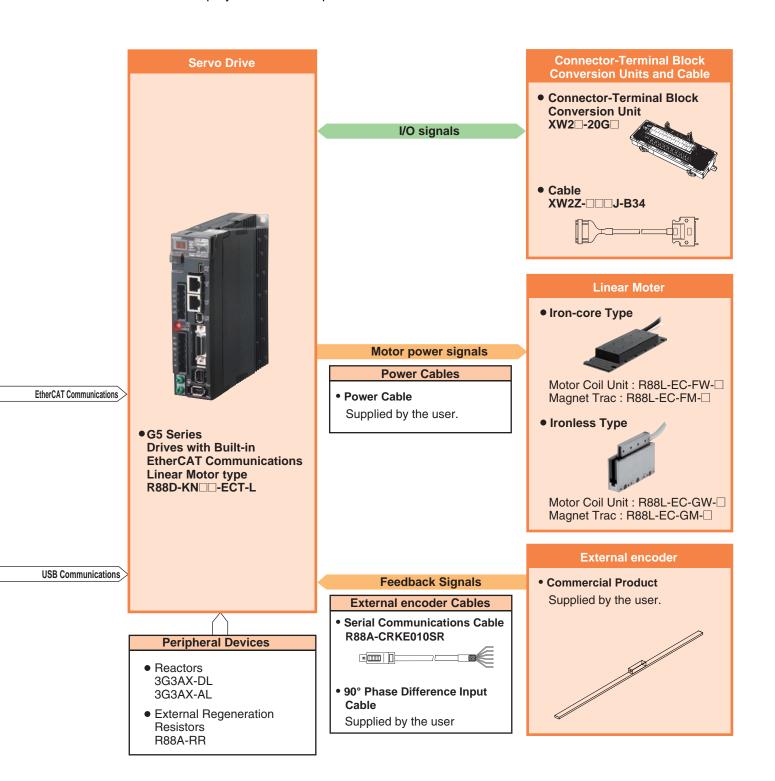
 CX-One FA Integrated Tool Package (Including CX-Drive)



Linear Motor for Higher-speed and **Higher-precision**

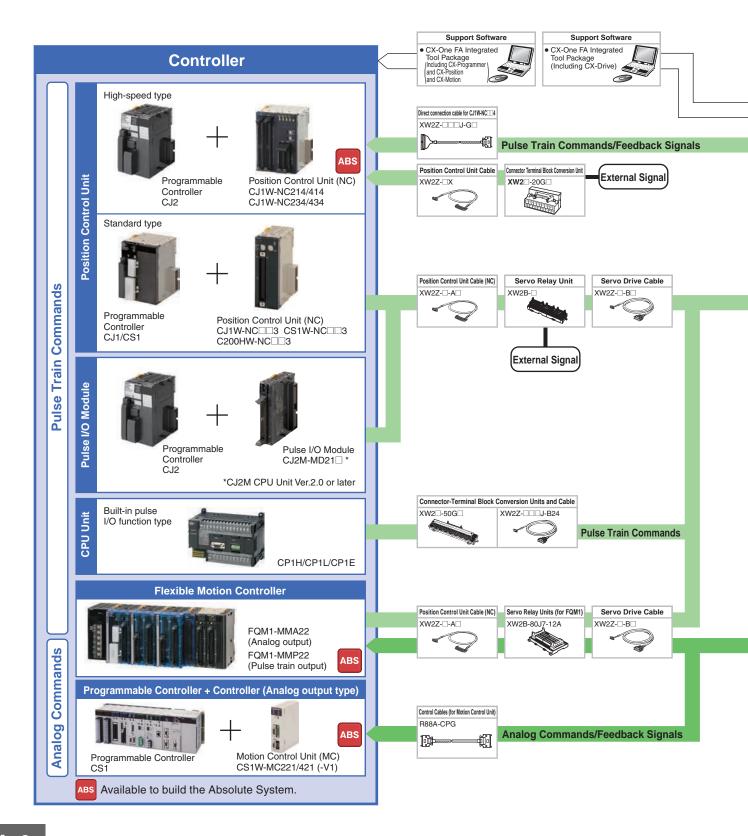
- Inherited functions and performance of G5 series and EtherCAT communications achieve high-speed and high-precision positioning.
- Lineup of compact and high-thrust iron-core motor type and cogging-free ironless motor type with excellent speed stability.
- Same Iron-core motor type for 200V AC and 400V AC.
- Quick setup by automatic setup function.





R88M-K/R88D-KT

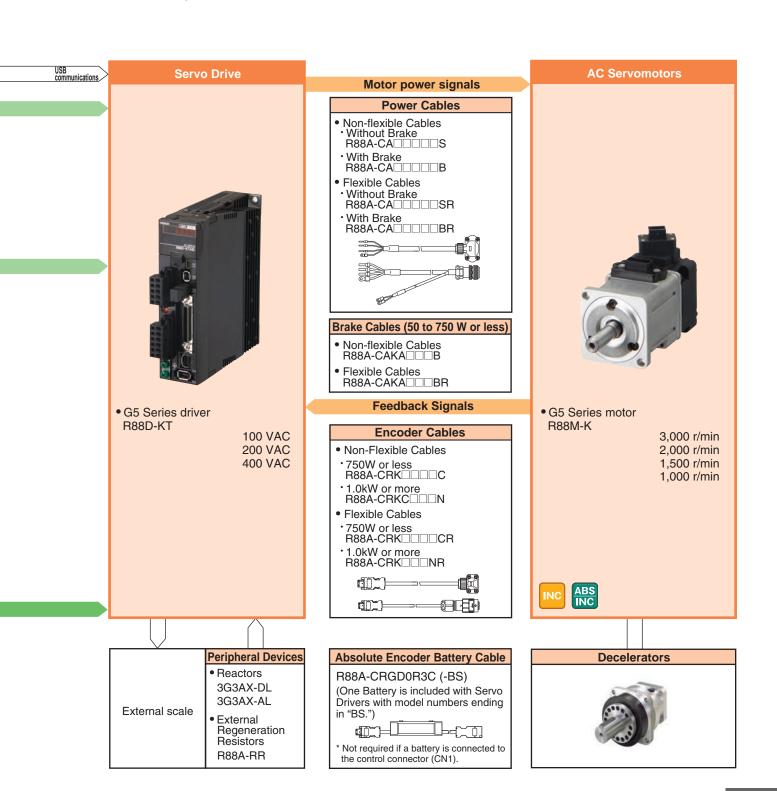
System Configuration



The Preeminent Servo That Revolutionizes Motion Controll

- Industry Top-class Tracking Performance.
 Speed Response Frequency of 2 kHz.
- Best Positioning Accuracy*.
 Featuring a 20-bit high-resolution incremental encoder.
 *8 times the resolution of previous OMRON models
- High-precision Positioning.
 Fully Closed Loop Control Is a Standard Feature.
- Conforms to the Latest International Standards.
 Safety and Productivity.
- Globalization. Lineup of 400 VAC Servomotors.





R88M-K/R88D-KN -ML2

System Configuration

Controllers (MECHATROLINK-II type)





Support Software

CX-One FA Integrated Tool Package Including CX-Programmer and CX-Position and CX-Motion

Support Software

CX-One FA Integrated Tool Package (Including CX-Drive)

MECHATROLINK-II

MECHATROLINK-II Cables

(With ring core and USB connector on both ends) FNY-W6003- (OMRON model number) (Without ring core USB connector on both ends) FNY-W6002- (OMRON model number)

MECHATROLINK-II Repeater

		Maximum transmission distance		
		0 to 30 m	30 to 50 m	
Number of	nber of	1 to 15	Repeater not required.	Repeater not required.
connected devices		16	Repeater not required.	Repeater required.

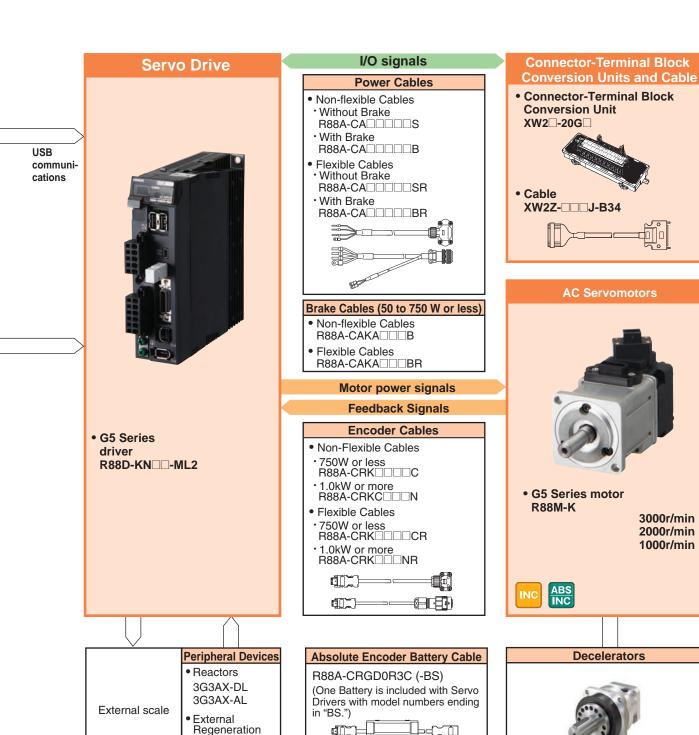
High-Speed and High-Precision G5 Series MECHATROLINK-II Communications with the Controller

• Data transfer using MECHATROLINK-II Communications:

All control data that can be interfaced between the Servo Driver and the Controller is transmitted using data communications. This enables maximizing the Servomotor performance without restricting the transmission performance of the control signals.

 Having a communications module built into the Servo Driver significantly saves space in the control panel.





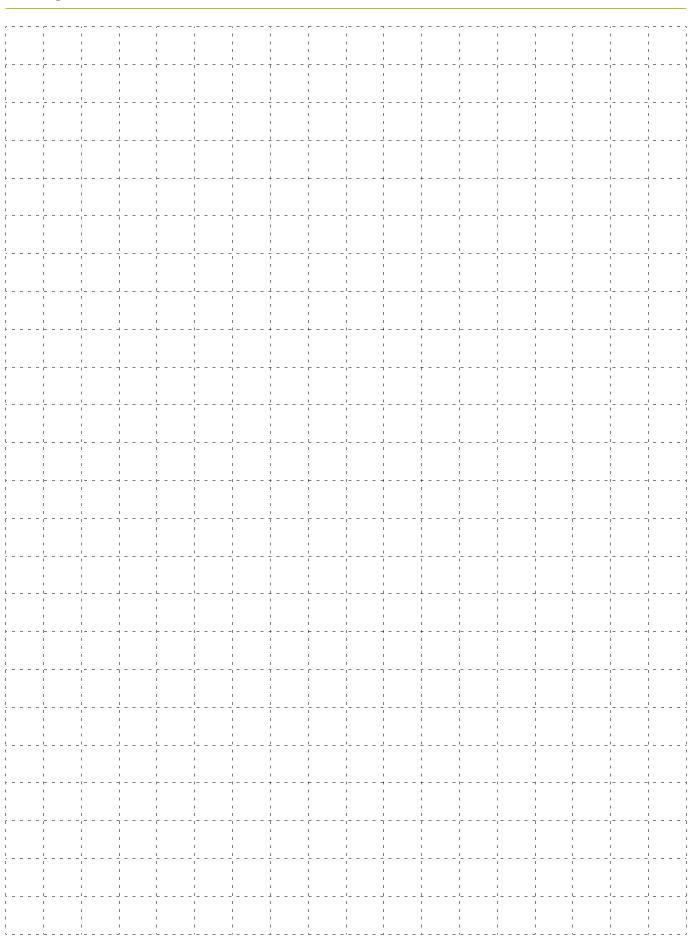
Not required if a battery is connected to

the control connector (CN1).

Rešistors

R88A-RR

MEMO



Ordering Information

Product name	AC Servomotors / Linear Motors / Servo Drives G5-series
Interpreting Mod	lel NumbersB-2
■ AC Servo ■ AC Servo ■ Linear Mo ■ Understa	Drive Rotary Motor Type Model Numbers Drive Linear Motor Type Model Numbers Drive Linear Motor Type Model Numbers Drive Rotary Model Numbers Drive Rotary Motor Type Model Numbers Drive Rotary Motor Type Model Numbers Drive Rotary Motor Type Model Numbers Drive Linear Motor Type Model Numbers Drive Linear Motor Type Model Numbers Drive Model Numbers Drive Linear Motor Type Model Numbers Drive Model Numbers Dri
Table of AC Serv	omotor VariationsB-5
Ordering Informa	ationB-6
EtherC Linear Genera	B-6 CAT Communications Motor with built-in EtherCAT communications al-purpose Inputs ATROLINK-II Communications
Linear Motors Decelerators (Accessories a	B-7
(Non-f	on Cables (Power Cables, Brake Cables, Encoder Cables) lexible Cables) le Cables)
■ Commun ●For ME	
■ Periphera (External ■ Support	Regeneration Resistors, Reactors, Mounting Brackets)
Combination tab	leB-25
■ AC Servo ■ Linear Mo	Drive and Servomotor Combinations omotor and Decelerator Combinations otor and AC Servo Drive Linear Motor Type Combinations or Combinations mbinations
Related Manuals	sB-37

As a Sysmac Device, the G5-series AC Servomotor/Servo Drive with Built-in EtherCAT Communications is designed to provide optimal functionality and enhanced operability when used in conjunction with a Machine Automation Controller such as NJ series and the automation software Sysmac Studio. Sysmac Device is a generic term for OMRON control devices such as an EtherCAT Slave, designed with unified communications specifications and user interface specifications.

When connecting a Servo Drive to the NJ5 series Machine Automation Controller, it is recommended that you use the Servo Drive with Built-in EtherCAT Communications, R88D-KN $\square\square$ -ECT, with unit version 2.1 or later.

Interpreting Model Numbers

AC Servo Drive Rotary Motor Type Model Numbers

R88D-K N 01 H -ECT

(2) (3) (4)

No	Item	Symbol	Specifications
(1)	G5-series Servo Drive		
(0)	D: T	Т	Analog input/Pulse train input type
(2)	Drive Type	N	Communication type
		A5	50 W
		01	100 W
		02	200 W
		04	400 W
		06	600 W
	Maximum	08	750 W
(3)	Applicable	10	1 kW
(3)	Servomotor Capacity	15	1.5 kW
		20	2 kW
		30	3 kW
		40	4 kW
		50	5 kW
		75	7.5 kW
		150	15 kW
	D 0 1	L	100 VAC
(4)	Power Supply Voltage	Н	200 VAC
		F	400 VAC
		Blank	General-purpose Inputs
(5)	Network type	-ML2	MECHATROLINK-II Communications
		-ECT	EtherCAT Communications

AC Servo Drive Linear Motor Type Model Numbers

R88D-K N 01 H -ECT -L

 $\frac{}{}$ (2) (3) (4) (5) (6)

No	Item	Symbol	Specifications
(1)		G5-se	eries Servo Drive
(2)	Drive Type	N	Communication type
		01	100 W
		02	200 W
		04	400 W
	Maximum Applicable Linear Motor Capacity	06	600 W
(3)		08	750 W
		10	1 kW
		15	1.5 kW
		20	2 kW
		30	3 kW
		L	100 VAC
(4)	Power Supply Voltage	Н	200 VAC
	vollage	F	400 VAC
(5)	Network type	-ECT	EtherCAT Communications
(6)	Motor type	-L	Linear Motor

AC Servomotor Model Numbers

R88M-K □ **750 30 H -BO S2**

(2) (3) (4) (5)

No	Item	Symbol	Specifications		
(1)	G5-series Servomotor				
(0)	Matau Tura	Blank	Cylinder type		
(2)	Motor Type	-	_		
		050	50 W		
		100	100 W		
		200	200 W		
		400	400 W		
		600	600 W		
		750	750 W		
		900	900 W		
		1K0	1 kW		
	Servomotor	1K5	1.5 kW		
(3)	Capacity	2K0	2 kW		
		3K0	3 kW		
		4K0	4 kW		
		4K5	4.5 kW		
		5K0	5 kW		
		6K0	6 kW		
		7K5	7.5 kW		
		11K0	11 kW		
		15K0	15 kW		
		10	1,000 r/min		
	Rated Rotation	15	1,500 r/min		
(4)	Speed	20	2,000 r/min		
		30	3,000 r/min		
			400 VAC		
		F	(with incremental encoder specifications)		
		н	200 VAC (with incremental encoder specifications)		
(E)	Applied Voltage	L	100 VAC (with incremental encoder specifications)		
(5)	Applied Voltage	С	400 VAC (with absolute encoder specifications) ABS/INC		
		Т	200VAC (with absolute encoder specifications) ABS/INC		
		S	100 VAC (with absolute encoder specifications) ABS/INC		
		Blank	Straight shaft		
(e)	Ontion	В	With brake		
(6)	Option	0	With oil seal		
	1	S2	With key and tap		

ABS/INC incremental encoder: 17bit, absolute encoder: 17bit

Linear Motor

● Iron-core linear motor

Motor Coil Unit

R88L-EC -FW -03 03 -A NP C

(1)

(2)

(3) (4) (5) (6)

Magnet Trac

R88L-EC -FM -03 096 -A

(1)

No	Item	Symbol	Specifications
(1)		G5-se	ries Linear Motor
(2)	Part Type FW		Iron-core type Motor Coil Unit
		03	30mm
(3)	Effective Magnet Width	06	60mm
	Widaii	11	110mm
	Coil Model	03	3-coil
		06	6-coil
(4)		09	9-coil
		12	12-coil
		15	15-coil
(5)	Version	Α	Ver.A
(6)	Connector	NP	Not Provided
(7)	Туре	С	Compact type

No	Item	Symbol	Specifications
(1)		G5-se	ries Linear Motor
(2)	Part Type	FM	Iron-core type Magnet Trac
		03	30mm
(3)	Effective Magnet Width	06	60mm
	Widai	11	110mm
		096	96mm
		144	144mm
(4)	Magnet Trac Unit Length	192	192mm
	Longar	288	288mm
		384	384mm
(5)	Version	Α	Ver.A

Ironless linear motor

Motor Coil Unit

R88L-EC -GW -03 03 -A NP S

(3) (4) (5) (6) (7)

Magnet Trac

R88L-EC -GM -03 090 -A

(1)

3

4 5

No	Item	Symbol	Specifications	No	
(1)	G5-series Linear Motor		ries Linear Motor	(1)	
(2)	Part Type	GW	Ironless type Motor Coil Unit	(2)	Pa
		03	30mm		
(3)	Effective Magnet Width	05	50mm	(3)	Effect
	Width	07	70mm	_	
		03	3-coil		
(4)	Coil Model	06	6-coil	_	
		09	9-coil	_	
(5)	Version	Α	Ver.A	_	
(6)	Connector	NP	Not Provided	- (4)	Magn
(7)	Туре	S	Standard type	- (4)	١

No	Item	Symbol	Specifications	
(1)	G5-series Linear Motor			
(2)	Part Type	GM	Ironless type Magnet Trac	
		03	30mm	
(3)	Effective Magnet Width	05	50mm	
		07	70mm	
		090	90mm	
	Magnet Trac Unit Length	114	114mm	
		120	120mm	
		126	126mm	
(4)		168	168mm	
(4)		171	171mm	
		210	210mm	
		390	390mm	
		456	456mm	
		546	546mm	
(5)	Version	Α	Ver.A	

Understanding Decelerator Model Numbers (Backlash = 3' Max./Backlash = 15' Max.)

Backlash = 3' Max.

R88G-HPG 14A 05 100 S B J

(2) (3) (4) (5) (6) (7)

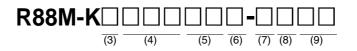
No	Item	Symbol	Specifications		
(1)	Decelerator for				
	G⊔-S	1	omotors Backlash = 3' Max.		
		11B	□40 —		
		14A	□60		
(2)	Flange Size	20A	□90		
()	Number	32A	□120		
		50A	□170		
		65A	□230		
		05	1/5		
		09	1/9 (only frame number 11B)		
		11	1/11 (except frame number 65A)		
		12	1/12 (only frame number 65A)		
(3)	Gear Ratio	20	1/20 (only frame number 65A)		
		21	1/21 (except frame number 65A)		
		25	1/25 (only frame number 65A)		
		33	1/33		
		45	1/45		
	Assiliantia	050	50 W		
		100	100 W		
		200	200 W		
		400	400 W		
		750	750 W		
		900	900 W		
(4)	Applicable Servomotor	1K0	1 kW		
. ,	Capacity	1K5	1.5 kW		
		2K0	2 kW		
		3K0	3 kW		
		4K0	4 kW		
		4K5	4.5 kW		
		5K0	5 kW		
		Blank	3,000-r/min cylindrical servomotors		
		_	-		
(5)	Motor Type	S	2,000-r/min cylindrical servomotors		
		Т	1,000-r/min cylindrical servomotors		
(6)	Backlash	В	Backlash = 3' Max		
	240.1140.1	Blank	Straight shaft		
(7)	Option	J	With key and tap		

Backlash = 15' Max.

R88G-VRSF 09 B 100

No	Item	Symbol	Specifications		
(1)	G□-Se		ecelerator for motors Backlash = 15' Max.		
		05	1/5		
(0)	0 5 "	09	1/9		
(2)	Gear Ratio	15	1/15		
		25	1/25		
		В	□52		
(3)	Flange Size Number	С	□78		
	Number	D	□98		
	Applicable Servomotor	050	50 W		
		100	100 W		
(4)		200	200 W		
	Capacity	400	400 W		
		750	750 W		
(5)	M-4 T	Blank	3,000-r/min cylindrical servomotor		
(5)	iviotor Type	Motor Type – –			
(6)	Backlash	С	Backlash = 15' Max		
(7)	Option	J	With key (without tap)		

Table of AC Servomotor Variations



(3)	(4)	(5)				(6)			(7)	3)	3)	(9))
				Applied Voltage						With I	orake /				
	Applicable Servomotor Capacity	Rotation speed	Model	INC	INC	INC	ABS	ABS	ABS	Withou	t brake	Model oil s		Shaft	type
Type			Model	400	200	100	400	200	100	-	В	0113	cuis		
				F	н	L	С	Т	s	Blank	With brake	Blank	0	Blank	S2
	50 W		R88M-K05030 *1		√			√		√	√	√	√	√	√
	100 W	-	R88M-K10030		V	√		√	V	V	√	√	√	√	√
	200 W		R88M-K20030		V	√		√	V	V	√	√	√	√	√
	400 W		R88M-K40030		√	√		V	√	√	V	√	√	V	V
	750 W		R88M-K75030	√	√		√	V		√	√	√	√	V	√
	1 kW	3,000 r/min	R88M-K1K030	√	√		√	V		√	√	√	√	V	√
	1.5 kW		R88M-K1K530	√	√		√	V		√	√	√	√	√	√
	2 kW		R88M-K2K030	√	√		√	√		√	√	√	√	√	√
	3 kW		R88M-K3K030	√	√		√	√		√	√	√	√	√	√
	4 kW	-	R88M-K4K030	√	√		√	√		√	√	√	√	√	√
	5 kW		R88M-K5K030	√	√		√	√		√	√	√	√	√	√
	400 W	2,000 r/min	R88M-K40020	√			√			√	√	√	√	√	√
	600 W		R88M-K60020	√			√			√	V	√	$\sqrt{}$	√	$\sqrt{}$
Cylinder	1 kW		R88M-K1K020	√	√		√	V		√	V	V	√	√	\checkmark
	1.5 kW		R88M-K1K520	√	√		√	V		√	V	V	√	√	\checkmark
	2 kW		R88M-K2K020	√	√		√	V		√	V	V	√	V	√
	3 kW		R88M-K3K020	√	√		√	V		√	√	√	$\sqrt{}$	V	√
	4 kW		R88M-K4K020	√	√		√	V		√	√	√	$\sqrt{}$	V	√
	5 kW		R88M-K5K020	√	√		√	V		√	V	V	√	V	√
	7.5 kW		R88M-K7K515 *2				√	V		√	1	√	$\sqrt{}$	V	√
	11 kW		R88M-K11K015 *2				√	V		√	1	√	$\sqrt{}$	V	√
	15 kW		R88M-K15K015 *2				√	√		√	√	√	$\sqrt{}$	√	\checkmark
	900 W		R88M-K90010	√	√		√	V		√	V	V	√	√	√
	2 kW		R88M-K2K010	√	√		√	V		√	V	V	√	√	√
	3 kW	1,000 r/min	R88M-K3K010	√	√		√	V		√	V	√	√	√	√
	4.5 kW		R88M-K4K510				√	V		√	V	√	√	√	√
	6 kW		R88M-K6K010				√	V		√	V	V	√	√	√
Blank: Cylinder type	example 030: 30 W 100: 100 W 1K0: 1 kW	10: 1,000 r/min 20: 2,000 r/min 30: 3,000 r/min		H: 200 L: 100 C: 400 T: 200	VAC (wi VAC (wi VAC (wi VAC (wi	th increi th increr th absol th absol	mental e nental er ute enco ute enco	ncoder) ncoder) ncoder) oder) AB oder) AB	INC INC S/INC	Blank: Withou brake B: 24 VD With b	C	Blank: Withou seals O: With seals	ıt oil	Blank: Straigh S2: With ke	

^{*1.} R88M-K05030H-□, R88M-K05030T-□, can be used for Power Supply Voltage of 100/200VAC. ***2.** The rated speed is 1,500 r/min.

Ordering Information

AC Servo Drives

EtherCAT Communications

Specif	ications					
Power Model Supply Voltage	Applicable Servomotor Capacity	Model				
	50 W	R88D-KNA5L-ECT				
Single-phase	100 W	R88D-KN01L-ECT				
100 VAC	200 W	R88D-KN02L-ECT				
	400 W	R88D-KN04L-ECT				
	100 W	R88D-KN01H-ECT				
Single-	200 W	R88D-KN02H-ECT				
phase/three-	400 W	R88D-KN04H-ECT				
phase	750 W	R88D-KN08H-ECT				
200 VAC	1 kW	R88D-KN10H-ECT				
	1.5 kW	R88D-KN15H-ECT				
	2 kW	R88D-KN20H-ECT				
	3 kW	R88D-KN30H-ECT				
Three-phase 200 VAC	5 kW	R88D-KN50H-ECT				
200 1710	7.5 kW	R88D-KN75H-ECT				
	15 kW	R88D-KN150H-ECT				
	600 W	R88D-KN06F-ECT				
	1 kW	R88D-KN10F-ECT				
	1.5 kW	R88D-KN15F-ECT				
Three-phase	2 kW	R88D-KN20F-ECT				
400 VAC	3 kW	R88D-KN30F-ECT				
	5 kW	R88D-KN50F-ECT				
	7.5 kW	R88D-KN75F-ECT				
	15 kW	R88D-KN150F-ECT				

Note: When connecting a Servo Drive to the NJ5 series Machine Automation Controller, it is recommended that you use the Servo Drive with Built-in EtherCAT Communications, R88D-KN□□□-ECT, with unit version 2.1 or later.

General-purpose Inputs (Analog input/Pulse train input type)

Specif	ications			
Power Supply Voltage	Applicable Servomotor Capacity	Model		
	50 W	R88D-KTA5L		
Single-phase	100 W	R88D-KT01L		
100 VAC	200 W	R88D-KT02L		
	400 W	R88D-KT04L		
	100 W	R88D-KT01H		
Single-	200 W	R88D-KT02H		
phase/three-	400 W	R88D-KT04H		
phase 200 VAC	750 W	R88D-KT08H		
200 VAC	1 kW	R88D-KT10H		
	1.5 kW	R88D-KT15H		
	2 kW	R88D-KT20H		
	3 kW	R88D-KT30H		
Three-phase 200 VAC	5 kW	R88D-KT50H		
	7.5 kW	R88D-KT75H		
	15 kW	R88D-KT150H		
	600 W	R88D-KT06F		
	1 kW	R88D-KT10F		
	1.5 kW	R88D-KT15F		
Three-phase	2 kW	R88D-KT20F		
400 VAC	3 kW	R88D-KT30F		
	5 kW	R88D-KT50F		
	7.5 kW	R88D-KT75F		
	15 kW	R88D-KT150F		

Linear Motor with built-in EtherCAT communications NEW

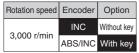
Specif	ications					
Power Supply Voltage	Applicable Servomotor Capacity	Model				
a	100 W	R88D-KN01L-ECT-L				
Single-phase 100 VAC	200 W	R88D-KN02L-ECT-L				
	400 W	R88D-KN04L-ECT-L				
	100 W	R88D-KN01H-ECT-L				
Single-	200 W	R88D-KN02H-ECT-L				
phase/three-	400 W	R88D-KN04H-ECT-L				
phase 200 VAC	750 W	R88D-KN08H-ECT-L				
200 VAC	1 kW	R88D-KN10H-ECT-L				
	1.5 kW	R88D-KN15H-ECT-L				
	600 W	R88D-KN06F-ECT-L				
	1 kW	R88D-KN10F-ECT-L				
Three-phase 400 VAC	1.5 kW	R88D-KN15F-ECT-L				
	2 kW	R88D-KN20F-ECT-L				
	3 kW	R88D-KN30F-ECT-L				

MECHATROLINK-II Communications

Specif	ications	
Power Supply Voltage	Applicable Servomotor Capacity	Model
	50 W	R88D-KNA5L-ML2
Single-phase	100 W	R88D-KN01L-ML2
100 VAC	200 W	R88D-KN02L-ML2
	400 W	R88D-KN04L-ML2
	100 W	R88D-KN01H-ML2
Single-	200 W	R88D-KN02H-ML2
phase/three-	400 W	R88D-KN04H-ML2
phase 200 VAC	750 W	R88D-KN08H-ML2
200 VAC	1 kW	R88D-KN10H-ML2
	1.5 kW	R88D-KN15H-ML2
	2 kW	R88D-KN20H-ML2
Three-phase 200 VAC	3 kW	R88D-KN30H-ML2
200 VAG	5 kW	R88D-KN50H-ML2
	600 W	R88D-KN06F-ML2
	1 kW	R88D-KN10F-ML2
Three-phase	1.5 kW	R88D-KN15F-ML2
400 VAC	2 kW	R88D-KN20F-ML2
	3 kW	R88D-KN30F-ML2
	5 kW	R88D-KN50F-ML2

AC Servomotors

<Cylinder Type> 3,000-r/min servomotors



			Model
	Specificat	ions	With incremental encoder
			Straight shaft with key and tap
	Voltage	Rated output	Without oil seals
		50 W	R88M-K05030H-S2
	400.1/	100 W	R88M-K10030L-S2
	100 V	200 W	R88M-K20030L-S2
_		400 W	R88M-K40030L-S2
		50 W	R88M-K05030H-S2
		100 W	R88M-K10030H-S2
		200 W	R88M-K20030H-S2
		400 W	R88M-K40030H-S2
		750 W	R88M-K75030H-S2
ake	200 V	1 kW	R88M-K1K030H-S2
t br		1.5 kW	R88M-K1K530H-S2
סנ		2 kW	R88M-K2K030H-S2
Without brake		3 kW	R88M-K3K030H-S2
		4 kW	R88M-K4K030H-S2
		5 kW	R88M-K5K030H-S2
		750 W	R88M-K75030F-S2
		1 kW	R88M-K1K030F-S2
	400 V	1.5 kW	R88M-K1K530F-S2
		2 kW	R88M-K2K030F-S2
		3 kW	R88M-K3K030F-S2
		4 kW	R88M-K4K030F-S2
		5 kW	R88M-K5K030F-S2
		50 W	R88M-K05030H-BS2
	400.1/	100 W	R88M-K10030L-BS2
	100 V	200 W	R88M-K20030L-BS2
		400 W	R88M-K40030L-BS2
		50 W	R88M-K05030H-BS2
		100 W	R88M-K10030H-BS2
		200 W	R88M-K20030H-BS2
		400 W	R88M-K40030H-BS2
		750 W	R88M-K75030H-BS2
e	200 V	1 kW	R88M-K1K030H-BS2
brake		1.5 kW	R88M-K1K530H-BS2
£		2 kW	R88M-K2K030H-BS2
⋛		3 kW	R88M-K3K030H-BS2
		4 kW	R88M-K4K030H-BS2
		5 kW	R88M-K5K030H-BS2
		750 W	R88M-K75030F-BS2
		1 kW	R88M-K1K030F-BS2
		1.5 kW	R88M-K1K530F-BS2
	400 V	2 kW	R88M-K2K030F-BS2
		3 kW	R88M-K3K030F-BS2
		4 kW	R88M-K4K030F-BS2
		5 kW	R88M-K5K030F-BS2

Rotation speed	Encoder	Option		
0.000 -/	INC	Without key		
3,000 r/min	ABS/INC	With key		

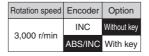
			Model				
Specifications			With incremental encoder				
			Straight shaft without key				
	Voltage	Rated output	Without oil seals				
		50 W	R88M-K05030H				
	100 V	100 W	R88M-K10030L				
	100 V	200 W	R88M-K20030L				
		400 W	R88M-K40030L				
		50 W	R88M-K05030H				
		100 W	R88M-K10030H				
		200 W	R88M-K20030H				
		400 W	R88M-K40030H				
		750 W	R88M-K75030H				
ake	200 V	1 kW	R88M-K1K030H				
Without brake		1.5 kW	R88M-K1K530H				
hou		2 kW	R88M-K2K030H				
Wit		3 kW	R88M-K3K030H				
		4 kW	R88M-K4K030H				
		5 kW	R88M-K5K030H				
	400 V	750 W	R88M-K75030F				
		1 kW	R88M-K1K030F				
		1.5 kW	R88M-K1K530F				
		2 kW	R88M-K2K030F				
		3 kW	R88M-K3K030F				
		4 kW	R88M-K4K030F				
		5 kW	R88M-K5K030F				
		50 W	R88M-K05030H-B				
	100 V	100 W	R88M-K10030L-B				
		200 W	R88M-K20030L-B				
		400 W	R88M-K40030L-B				
		50 W	R88M-K05030H-B				
		100 W	R88M-K10030H-B				
		200 W	R88M-K20030H-B				
		400 W	R88M-K40030H-B				
		750 W	R88M-K75030H-B				
ke	200 V	1 kW	R88M-K1K030H-B				
bra		1.5 kW	R88M-K1K530H-B				
With brake		2 kW	R88M-K2K030H-B				
5		3 kW	R88M-K3K030H-B				
		4 kW	R88M-K4K030H-B				
		5 kW	R88M-K5K030H-B				
		750 W	R88M-K75030F-B				
		1 kW	R88M-K1K030F-B				
		1.5 kW	R88M-K1K530F-B				
	400 V	2 kW	R88M-K2K030F-B				
		3 kW	R88M-K3K030F-B				
		4 kW	R88M-K4K030F-B				
Note:		5 kW	R88M-K5K030F-B				

AC Servomotor/Drive G5-series



			Model				
	Specificat	ions	With absolute encoder				
			Straight shaft withkey and tap				
	Voltage	Rated output	Without oil seals				
		50 W	R88M-K05030T-S2				
	100 V	100 W	R88M-K10030S-S2				
		200 W	R88M-K20030S-S2				
		400 W	R88M-K40030S-S2				
		50 W	R88M-K05030T-S2				
		100 W	R88M-K10030T-S2				
		200 W	R88M-K20030T-S2				
		400 W	R88M-K40030T-S2				
ω		750 W	R88M-K75030T-S2				
rak	200 V	1 kW	R88M-K1K030T-S2				
ut b		1.5 kW	R88M-K1K530T-S2				
Without brake		2 kW	R88M-K2K030T-S2				
≶		3 kW	R88M-K3K030T-S2				
		4 kW	R88M-K4K030T-S2				
		5 kW	R88M-K5K030T-S2				
		750 W	R88M-K75030C-S2				
	400 V	1 kW	R88M-K1K030C-S2				
		1.5 kW	R88M-K1K530C-S2				
		2 kW	R88M-K2K030C-S2				
		3 kW 4 kW	R88M-K3K030C-S2 R88M-K4K030C-S2				
		5 kW	R88M-K5K030C-S2				
		50 W	R88M-K05030T-BS2				
	100 V	100 W	R88M-K10030S-BS2				
		200 W	R88M-K20030S-BS2				
		400 W	R88M-K40030S-BS2				
		50 W	R88M-K05030T-BS2				
		100 W	R88M-K10030T-BS2				
		200 W	R88M-K20030T-BS2				
		400 W	R88M-K40030T-BS2				
		750 W	R88M-K75030T-BS2				
Φ	200 V	1 kW	R88M-K1K030T-BS2				
ith brake		1.5 kW	R88M-K1K530T-BS2				
ŧ		2 kW	R88M-K2K030T-BS2				
≶		3 kW	R88M-K3K030T-BS2				
		4 kW	R88M-K4K030T-BS2				
		5 kW	R88M-K5K030T-BS2				
		750 W	R88M-K75030C-BS2				
		1 kW	R88M-K1K030C-BS2				
		1.5 kW	R88M-K1K530C-BS2				
	400 V	2 kW	R88M-K2K030C-BS2				
		3 kW	R88M-K3K030C-BS2				
		4 kW	R88M-K4K030C-BS2				
		5 kW	R88M-K5K030C-BS2				
Noto	Modele	th oil ooolo	are also available				

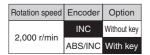
Note:	Models	with o	OIL	seals	are	also	available.



			Model	
	Specifications		With absolute encoder	
			Straight shaft without key	
	Voltage Rated output		Without oil seals	
		50 W	R88M-K05030T	
	100 V	100 W	R88M-K10030S	
	100 0	200 W	R88M-K20030S	
		400 W	R88M-K40030S	
		50 W	R88M-K05030T	
		100 W	R88M-K10030T	
		200 W	R88M-K20030T	
		400 W	R88M-K40030T	
4		750 W	R88M-K75030T	
ake	200 V	1 kW	R88M-K1K030T	
Without brake		1.5 kW	R88M-K1K530T	
يَ		2 kW	R88M-K2K030T	
₹		3 kW	R88M-K3K030T	
		4 kW	R88M-K4K030T	
		5 kW	R88M-K5K030T	
		750 W	R88M-K75030C	
		1 kW	R88M-K1K030C	
	400 V	1.5 kW	R88M-K1K530C	
		2 kW	R88M-K2K030C	
		3 kW	R88M-K3K030C	
		4 kW	R88M-K4K030C	
		5 kW	R88M-K5K030C	
		50 W	R88M-K05030T-B	
	100 V	100 W	R88M-K10030S-B	
		200 W	R88M-K20030S-B	
		400 W	R88M-K40030S-B	
		50 W	R88M-K05030T-B	
		100 W	R88M-K10030T-B	
		200 W 400 W	R88M-K20030T-B	
		750 W	R88M-K40030T-B R88M-K75030T-B	
	200 V	1 kW	R88M-K1K030T-B	
äke	200 V	1.5 kW	R88M-K1K530T-B	
With brake		2 kW	R88M-K2K030T-B	
Ž		3 kW	R88M-K3K030T-B	
		4 kW	R88M-K4K030T-B	
		5 kW	R88M-K5K030T-B	
		750 W	R88M-K75030C-B	
		1 kW	R88M-K1K030C-B	
		1.5 kW	R88M-K1K530C-B	
	400 V	2 kW	R88M-K2K030C-B	
	400 V	3 kW	R88M-K3K030C-B	
		4 kW	R88M-K4K030C-B	
		5 kW	R88M-K5K030C-B	
Mata	NA I - I	th all apple	noolvi-Nonoouc-B	

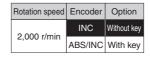
Ordering Informat

2,000-r/min servomotors



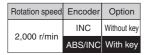
		Model	
Specifications		With incremental encoder Straight shaft with key and tap	
	1 kW	R88M-K1K020H-S2	
	1.5 kW	R88M-K1K520H-S2	
200 V	2 kW	R88M-K2K020H-S2	
200 V	3 kW	R88M-K3K020H-S2	
	4 kW	R88M-K4K020H-S2	
	5 kW	R88M-K5K020H-S2	
	400 W	R88M-K40020F-S2	
	600 W	R88M-K60020F-S2	
400 V	1 kW	R88M-K1K020F-S2	
	1.5 kW	R88M-K1K520F-S2	
	2 kW	R88M-K2K020F-S2	
	3 kW	R88M-K3K020F-S2	
	4 kW	R88M-K4K020F-S2	
	5 kW	R88M-K5K020F-S2	
	1 kW	R88M-K1K020H-BS2	
	1.5 kW	R88M-K1K520H-BS2	
200.1/	2 kW	R88M-K2K020H-BS2	
200 V	3 kW	R88M-K3K020H-BS2	
	4 kW	R88M-K4K020H-BS2	
	5 kW	R88M-K5K020H-BS2	
	400 W	R88M-K40020F-BS2	
	600 W	R88M-K60020F-BS2	
	1 kW	R88M-K1K020F-BS2	
400 V	1.5 kW	R88M-K1K520F-BS2	
400 V	2 kW	R88M-K2K020F-BS2	
	3 kW	R88M-K3K020F-BS2	
	4 kW	R88M-K4K020F-BS2	
	5 kW	R88M-K5K020F-BS2	
	Voltage 200 V	200 V Rated output 1 kW 1.5 kW 2 kW 3 kW 4 kW 5 kW 400 W 600 W 1 kW 1.5 kW 2 kW 3 kW 4 kW 5 kW 1 kW 5 kW 1 kW 1.5 kW 2 kW 3 kW 4 kW 5 kW 1 kW 1.5 kW 2 kW 3 kW 4 kW 5 kW	

Note: Models with oil seals are also available.



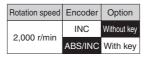
			Model	
	Specifications		With incremental encoder	
			Straight shaft without key	
	Voltage	Rated output	Without oil seals	
		1 kW	R88M-K1K020H	
		1.5 kW	R88M-K1K520H	
	200 V	2 kW	R88M-K2K020H	
	200 V	3 kW	R88M-K3K020H	
		4 kW	R88M-K4K020H	
ake		5 kW	R88M-K5K020H	
Without brake		400 W	R88M-K40020F	
hou		600 W	R88M-K60020F	
Wit	400 V	1 kW	R88M-K1K020F	
		1.5 kW	R88M-K1K520F	
		2 kW	R88M-K2K020F	
		3 kW	R88M-K3K020F	
		4 kW	R88M-K4K020F	
		5 kW	R88M-K5K020F	
		1 kW	R88M-K1K020H-B	
		1.5 kW	R88M-K1K520H-B	
	200 V	2 kW	R88M-K2K020H-B	
	200 V	3 kW	R88M-K3K020H-B	
		4 kW	R88M-K4K020H-B	
e		5 kW	R88M-K5K020H-B	
With brake		400 W	R88M-K40020F-B	
ith		600 W	R88M-K60020F-B	
>		1 kW	R88M-K1K020F-B	
	400 V	1.5 kW	R88M-K1K520F-B	
	400 V	2 kW	R88M-K2K020F-B	
		3 kW	R88M-K3K020F-B	
		4 kW	R88M-K4K020F-B	
		5 kW	R88M-K5K020F-B	

AC Servomotor/Drive G5-series



Specifications			Model	
		ions	With absolute encoder	
			Straight shaft with key and tap	
	Voltage	Rated output	Without oil seals	
		1 kW	R88M-K1K020T-S2	
		1.5 kW	R88M-K1K520T-S2	
		2 kW	R88M-K2K020T-S2	
		3 kW	R88M-K3K020T-S2	
	200 V	4 kW	R88M-K4K020T-S2	
		5 kW	R88M-K5K020T-S2	
		7.5 kW	R88M-K7K515T-S2 *	
		11 kW	R88M-K11K015T-S2 *	
ake		15 kW	R88M-K15K015T-S2 *	
t br		400 W	R88M-K40020C-S2	
Nithout brake		600 W	R88M-K60020C-S2	
Wit		1 kW	R88M-K1K020C-S2	
		1.5 kW	R88M-K1K520C-S2	
		2 kW	R88M-K2K020C-S2	
	400 V	3 kW	R88M-K3K020C-S2	
		4 kW	R88M-K4K020C-S2	
		5 kW	R88M-K5K020C-S2	
		7.5 kW	R88M-K7K515C -S2 *	
		11 kW	R88M-K11K015C-S2 *	
		15 kW	R88M-K15K015C-S2 *	
		1 kW	R88M-K1K020T-BS2	
		1.5 kW	R88M-K1K520T-BS2	
		2 kW	R88M-K2K020T-BS2	
		3 kW	R88M-K3K020T-BS2	
	200 V	4 kW	R88M-K4K020T-BS2	
		5 kW	R88M-K5K020T-BS2	
		7.5 kW	R88M-K7K515T-BS2 *	
		11 kW	R88M-K11K015T-BS2 *	
ķe		15 kW	R88M-K15K015T-BS2 *	
With brake		400 W	R88M-K40020C-BS2	
/ith		600 W	R88M-K60020C-BS2	
\$		1 kW	R88M-K1K020C-BS2	
		1.5 kW	R88M-K1K520C-BS2	
		2 kW	R88M-K2K020C-BS2	
	400 V	3 kW	R88M-K3K020C-BS2	
		4 kW	R88M-K4K020C-BS2	
		5 kW	R88M-K5K020C-BS2	
		7.5 kW	R88M-K7K515C-BS2 *	
		11 kW	R88M-K11K015C-BS2 *	
		15 kW	R88M-K15K015C-BS2 *	

Note: Models with oil seals are also available. * The rated speed is 1,500 r/min.



			Model With absolute encoder	
	Specifications			
			Straight shaft without key	
	Voltage	Rated output	Without oil seals	
		1 kW	R88M-K1K020T	
		1.5 kW	R88M-K1K520T	
		2 kW	R88M-K2K020T	
		3 kW	R88M-K3K020T	
	200 V	4 kW	R88M-K4K020T	
		5 kW	R88M-K5K020T	
		7.5 kW	R88M-K7K515T *	
		11 kW	R88M-K11K015T *	
Without brake		15 kW	R88M-K15K015T *	
t br		400 W	R88M-K40020C	
no T		600 W	R88M-K60020C	
Ž		1 kW	R88M-K1K020C	
		1.5 kW	R88M-K1K520C	
	400 V	2 kW	R88M-K2K020C	
		3 kW	R88M-K3K020C	
		4 kW	R88M-K4K020C	
		5 kW	R88M-K5K020C	
		7.5 kW	R88M-K7K515C *	
		11 kW	R88M-K11K015C *	
		15 kW	R88M-K15K015C *	
		1 kW	R88M-K1K020T-B	
		1.5 kW	R88M-K1K520T-B	
		2 kW	R88M-K2K020T-B	
		3 kW	R88M-K3K020T-B	
	200 V	4 kW	R88M-K4K020T-B	
		5 kW	R88M-K5K020T-B	
		7.5 kW	R88M-K7K515T-B *	
		11 kW	R88M-K11K015T-B *	
<u>8</u>		15 kW	R88M-K15K015T-B *	
With brake		400 W	R88M-K40020C-B	
jŧ.		600 W	R88M-K60020C-B	
>		1 kW	R88M-K1K020C-B	
		1.5 kW	R88M-K1K520C-B	
		2 kW	R88M-K2K020C-B	
	400 V	3 kW	R88M-K3K020C-B	
		4 kW	R88M-K4K020C-B	
		5 kW	R88M-K5K020C-B	
		7.5 kW	R88M-K7K515C-B *	
		11 kW	R88M-K11K015C-B *	
		15 kW	R88M-K15K015C-B *	

Note: Models with oil seals are also available. * The rated speed is 1,500 r/min.

1,000-r/min servomotors



Specifications			Model With incremental encoder	
		ions		
			Straight shaft with key and tap	
	Voltage	Rated output	Without oil seals	
		900 W	R88M-K90010H-S2	
Without brake	200 V	2 kW	R88M-K2K010H-S2	
t br		3 kW	R88M-K3K010H-S2	
noι	400 V	900 W	R88M-K90010F-S2	
Vit		2 kW	R88M-K2K010F-S2	
-		3 kW	R88M-K3K010F-S2	
		900 W	R88M-K90010H-BS2	
e	200 V	2 kW	R88M-K2K010H-BS2	
orał		3 kW	R88M-K3K010H-BS2	
With brake		900 W	R88M-K90010F-BS2	
>	400 V	2 kW	R88M-K2K010F-BS2	
		3 kW	R88M-K3K010F-BS2	

Note: Models with oil seals are also available.

Rotation speed	Encoder	Option
1 000 =/	INC	Without key
1,000 r/min	ABS/INC	With key

Specifications			Model
		ions	With incremental encoder
			Straight shaft without key
	Voltage Rated output		Without oil seals
		900 W	R88M-K90010H
ake	200 V	2 kW	R88M-K2K010H
Without brake		3 kW	R88M-K3K010H
οc	400 V	900 W	R88M-K90010F
E		2 kW	R88M-K2K010F
_		3 kW	R88M-K3K010F
		900 W	R88M-K90010H-B
ē	200 V	2 kW	R88M-K2K010H-B
With brake		3 kW	R88M-K3K010H-B
£ F		900 W	R88M-K90010F-B
≶	400 V	2 kW	R88M-K2K010F-B
		3 kW	R88M-K3K010F-B

Note: Models with oil seals are also available.

Rotation speed	Encoder	Option
4 000 -/!	INC	Without key
1,000 r/min	ABS/INC	With key

	Specifications		Model	
			With absolute encoder	
			Straight shaft with key and tap	
	Voltage	Rated output	Without oil seals	
		900 W	R88M-K90010T-S2	
		2 kW	R88M-K2K010T-S2	
	200 V	3 kW	R88M-K3K010T-S2	
ake		4.5 kW	R88M-K4K510T-S2	
Without brake		6 kW	R88M-K6K010T-S2	
	400 V	900 W	R88M-K90010C-S2	
		2 kW	R88M-K2K010C-S2	
		3 kW	R88M-K3K010C-S2	
		4.5 kW	R88M-K4K510C-S2	
		6 kW	R88M-K6K010C-S2	
		900 W	R88M-K90010T-BS2	
		2 kW	R88M-K2K010T-BS2	
	200 V	3 kW	R88M-K3K010T-BS2	
ē		4.5 kW	R88M-K4K510T-BS2	
ora		6 kW	R88M-K6K010T-BS2	
With brake		900 W	R88M-K90010C-BS2	
≥		2 kW	R88M-K2K010C-BS2	
	400 V	3 kW	R88M-K3K010C-BS2	
		4.5 kW	R88M-K4K510C-BS2	
		6 kW	R88M-K6K010C-BS2	

Note: Models with oil seals are also available.

Rotation speed	Encoder	Option
1,000 r/min	INC	Without key
	ABS/INC	With key

			Model	
	Specifications		With absolute encoder	
			Straight shaft without key	
	Voltage	Rated output	Without oil seals	
		900 W	R88M-K90010T	
		2 kW	R88M-K2K010T	
	200 V	3 kW	R88M-K3K010T	
ake		4.5 kW	R88M-K4K510T	
t Dr		6 kW	R88M-K6K010T	
Without brake	400 V	900 W	R88M-K90010C	
		2 kW	R88M-K2K010C	
		3 kW	R88M-K3K010C	
		4.5 kW	R88M-K4K510C	
		6 kW	R88M-K6K010C	
		900 W	R88M-K90010T-B	
		2 kW	R88M-K2K010T-B	
	200 V	3 kW	R88M-K3K010T-B	
ē		4.5 kW	R88M-K4K510T-B	
oral		6 kW	R88M-K6K010T-B	
With brake		900 W	R88M-K90010C-B	
≥		2 kW	R88M-K2K010C-B	
	400 V	3 kW	R88M-K3K010C-B	
		4.5 kW	R88M-K4K510C-B	
		6 kW	R88M-K6K010C-B	

Linear Motors <u>NEW</u> Core motor type> Motor Coil Unit

Motor Coil Unit model	Continuous force [N]	Momentary maximum force [N]
R88L-EC-FW-0303-ANPC	48	105
R88L-EC-FW-0306-ANPC	96	210
R88L-EC-FW-0606-ANPC	160	400
R88L-EC-FW-0609-ANPC	240	600
R88L-EC-FW-0612-ANPC	320	800
R88L-EC-FW-1112-ANPC	608	1600
R88L-EC-FW-1115-ANPC	760	2000

Magnet Trac

Magnet Trac model	Magnet Trac Unit Length (mm)
R88L-EC-FM-03096-A	96
R88L-EC-FM-03144-A	144
R88L-EC-FM-03384-A	384
R88L-EC-FM-06192-A	192
R88L-EC-FM-06288-A	288
R88L-EC-FM-11192-A	192
R88L-EC-FM-11288-A	288

<Ironless motor type> Motor Coil Unit

Motor Coil Unit model	Continuous force [N]	Momentary maximum force [N]
R88L-EC-GW-0303-ANPS	26.5	96
R88L-EC-GW-0306-ANPS	53	200
R88L-EC-GW-0309-ANPS	80	300
R88L-EC-GW-0503-ANPS	58	240
R88L-EC-GW-0506-ANPS	117	480
R88L-EC-GW-0509-ANPS	175	720
R88L-EC-GW-0703-ANPS	117	552
R88L-EC-GW-0706-ANPS	232	1110
R88L-EC-GW-0709-ANPS	348	1730

Magnet Trac

Magnet Trac model	Magnet Trac Unit Length (mm)
R88L-EC-GM-03090-A	90
R88L-EC-GM-03120-A	120
R88L-EC-GM-03390-A	390
R88L-EC-GM-05126-A	126
R88L-EC-GM-05168-A	168
R88L-EC-GM-05210-A	210
R88L-EC-GM-05546-A	546
R88L-EC-GM-07114-A	114
R88L-EC-GM-07171-A	171
R88L-EC-GM-07456-A	456

Combination table

Motor Coil Unit and Magnet Trac Combinations

Iron-core motor type

Motor Coil Unit model	Magnet Trac model
R88L-EC-FW-0303-ANPC R88L-EC-FW-0306-ANPC	R88L-EC-FM-03096-A R88L-EC-FM-03144-A R88L-EC-FM-03384-A
R88L-EC-FW-0606-ANPC R88L-EC-FW-0609-ANPC R88L-EC-FW-0612-ANPC	R88L-EC-FM-06192-A R88L-EC-FM-06288-A
R88L-EC-FW-1112-ANPC R88L-EC-FW-1115-ANPC	R88L-EC-FM-11192-A R88L-EC-FM-11288-A

Ironless motor type

Motor Coil Unit model	Magnet Trac model
R88L-EC-GW-0303-ANPS	R88L-EC-GM-03090-A
R88L-EC-GW-0306-ANPS	R88L-EC-GM-03120-A
R88L-EC-GW-0309-ANPS	R88L-EC-GM-03390-A
R88L-EC-GW-0503-ANPS R88L-EC-GW-0506-ANPS R88L-EC-GW-0509-ANPS	R88L-EC-GM-05126-A R88L-EC-GM-05168-A R88L-EC-GM-05210-A R88L-EC-GM-05546-A
R88L-EC-GW-0703-ANPS	R88L-EC-GM-07114-A
R88L-EC-GW-0706-ANPS	R88L-EC-GM-07171-A
R88L-EC-GW-0709-ANPS	R88L-EC-GM-07456-A

Decelerators (Backlash = 3' Max./Backlash = 15' Max.)

Backlash = 3' Max <Cylinder Type>

● 3,000-r/min servomotors

Straight shaft without key

Straight shaft without key			
Motor capacity	Gear Ratio	Model (Straight shaft)	
	1/5	R88G-HPG11B05100B	
	1/9	R88G-HPG11B09050B	
50 W	1/21	R88G-HPG14A21100B	
	1/33	R88G-HPG14A33050B	
	1/45	R88G-HPG14A45050B	
	1/5	R88G-HPG11B05100B	
	1/11	R88G-HPG14A11100B	
100 W	1/21	R88G-HPG14A21100B	
	1/33	R88G-HPG20A33100B	
	1/45	R88G-HPG20A45100B	
	1/5	R88G-HPG14A05200B	
	1/11	R88G-HPG14A11200B	
200 W	1/21	R88G-HPG20A21200B	
	1/33	R88G-HPG20A33200B	
	1/45	R88G-HPG20A45200B	
	1/5	R88G-HPG14A05400B	
	1/11	R88G-HPG20A11400B	
400 W	1/21	R88G-HPG20A21400B	
	1/33	R88G-HPG32A33400B	
	1/45	R88G-HPG32A45400B	
	1/5	R88G-HPG20A05750B	
	1/11	R88G-HPG20A11750B	
750 W	1/21	R88G-HPG32A21750B	
(200 V)	1/33	R88G-HPG32A33750B	
	1/45	R88G-HPG32A45750B	
	1/5	R88G-HPG32A052K0B	
	1/11	R88G-HPG32A112K0B	
750W	1/21	R88G-HPG32A11K5B	
(400 V)			
	1/33	R88G-HPG32A33600SB	
	1/45	R88G-HPG50A451K5B	
	1/5	R88G-HPG32A052K0B	
41.147	1/11	R88G-HPG32A112K0B	
1kW	1/21	R88G-HPG32A211K5B	
	1/33	R88G-HPG50A332K0B	
	1/45	R88G-HPG50A451K5B	
	1/5	R88G-HPG32A052K0B	
	1/11	R88G-HPG32A112K0B	
1.5kW	1/21	R88G-HPG32A211K5B	
	1/33	R88G-HPG50A332K0B	
	1/45	R88G-HPG50A451K5B	
	1/5	R88G-HPG32A052K0B	
2kW	1/11	R88G-HPG32A112K0B	
	1/21	R88G-HPG50A212K0B	
	1/33	R88G-HPG50A332K0B	
	1/5	R88G-HPG32A053K0B	
3kW	1/11	R88G-HPG50A113K0B	
	1/21	R88G-HPG50A213K0B	
4kW	1/5	R88G-HPG32A054K0B	
-T/VV	1/11	R88G-HPG50A115K0B	
FLAM	1/5	R88G-HPG50A055K0B	
5kW	.,,		

Note: 1. The standard models have a straight shaft.

● 2,000-r/min servomotors

Straight shaft without key

Motor capacity	Gear Ratio	Model (Straight shaft)	
	1/5	R88G-HPG32A052K0B	
	1/11	R88G-HPG32A112K0B	
400 W	1/21	R88G-HPG32A211K5B	
	1/33	R88G-HPG32A33600SB	
	1/45	R88G-HPG32A45400SB	
	1/5	R88G-HPG32A052K0B	
	1/11	R88G-HPG32A112K0B	
600 W	1/21	R88G-HPG32A211K5B	
	1/33	R88G-HPG32A33600SB	
	1/45	R88G-HPG50A451K5B	
	1/5	R88G-HPG32A053K0B	
	1/11	R88G-HPG32A112K0SB	
1 kW	1/21	R88G-HPG32A211K0SB	
	1/33	R88G-HPG50A332K0SB	
	1/45	R88G-HPG50A451K0SB	
	1/5	R88G-HPG32A053K0B	
4 5 100/	1/11	R88G-HPG32A112K0SB	
1.5 kW	1/21	R88G-HPG50A213K0B	
	1/33	R88G-HPG50A332K0SB	
	1/5	R88G-HPG32A053K0B	
2 kW	1/11	R88G-HPG32A112K0SB	
∠ KVV	1/21	R88G-HPG50A213K0B	
	1/33	R88G-HPG50A332K0SB	
	1/5	R88G-HPG32A054K0B	
3 kW	1/11	R88G-HPG50A115K0B	
3 KVV	1/21	R88G-HPG50A213K0SB	
	1/25	R88G-HPG65A253K0SB	
	1/5	R88G-HPG50A055K0SB	
4 kW	1/11	R88G-HPG50A115K0SB	
4 KVV	1/20	R88G-HPG65A205K0SB	
	1/25	R88G-HPG65A255K0SB	
	1/5	R88G-HPG50A055K0SB	
5 kW	1/11	R88G-HPG50A115K0SB	
O KVV	1/20	R88G-HPG65A205K0SB	
	1/25	R88G-HPG65A255K0SB	

Note: 1. The standard models have a straight shaft.

To order a Servomotor with a straight shaft with key, add "J" to the end of the model number, in the place indicated by the box.

To order a Servomotor with a straight shaft with key, add "J" to the end of the model number, in the place indicated by the box.

● 1,000-r/min servomotors

Straight shaft without key

Motor capacity	Gear Ratio	Model (Straight shaft)	
1/5		R88G-HPG32A05900TB	
900 W	1/11	R88G-HPG32A11900TB	
900 W	1/21	R88G-HPG50A21900TB	
	1/33	R88G-HPG50A33900TB	
	1/5	R88G-HPG32A052K0TB	
2 kW	1/11	R88G-HPG50A112K0TB	
	1/21	R88G-HPG50A212K0TB	
	1/25	R88G-HPG65A255K0SB	
	1/5	R88G-HPG50A055K0SB	
3 kW	1/11	R88G-HPG50A115K0SB	
3 KVV	1/20	R88G-HPG65A205K0SB	
	1/25	R88G-HPG65A255K0SB	

Note: 1. The standard models have a straight shaft.

2. To order a Servomotor with a straight shaft with key, add "J" to the end of the model number, in the place indicated by the

Backlash = 15' Max <Cylinder Type>

● 3,000-r/min servomotors

Straight shaft with key

Motor capacity	Gear Ratio	Model (Straight shaft)
	1/5	R88G-VRSF05B100CJ
50 W	1/9	R88G-VRSF09B100CJ
50 W	1/15	R88G-VRSF15B100CJ
	1/25	R88G-VRSF25B100CJ
	1/5	R88G-VRSF05B100CJ
100 W	1/9	R88G-VRSF09B100CJ
100 W	1/15	R88G-VRSF15B100CJ
	1/25	R88G-VRSF25B100CJ
	1/5	R88G-VRSF05B200CJ
000 W	1/9	R88G-VRSF09C200CJ
200 W	1/15	R88G-VRSF15C200CJ
	1/25	R88G-VRSF25C200CJ
	1/5	R88G-VRSF05C400CJ
400 W	1/9	R88G-VRSF09C400CJ
400 W	1/15	R88G-VRSF15C400CJ
	1/25	R88G-VRSF25C400CJ
	1/5	R88G-VRSF05C750CJ
750 W	1/9	R88G-VRSF09D750CJ
750 W	1/15	R88G-VRSF15D750CJ
	1/25	R88G-VRSF25D750CJ

Accessories and Cables

■ Connection Cables (Power Cables, Brake Cables, Encoder Cables) <Non-flexible Cables>

Power cable

0		Without brake	With brake
Specifications		Model	Model
	3 m	R88A-CAKA003S	
	5 m	R88A-CAKA005S	
	10 m	R88A-CAKA010S	
[100 V/200 V]	15m	R88A-CAKA015S	
3,000-r/min Servomotors of 50 to 750 W	20 m	R88A-CAKA020S	
	30 m	R88A-CAKA030S	
	40 m	R88A-CAKA040S	
	50 m	R88A-CAKA050S	
	3 m	R88A-CAGB003S	R88A-CAGB003B
	5 m	R88A-CAGB005S	R88A-CAGB005B
[200 V]	10 m	R88A-CAGB010S	R88A-CAGB010B
3,000-r/min Servomotors of 1 to 2 kW	15 m	R88A-CAGB015S	R88A-CAGB015B
2,000-r/min Servomotors of 1 to 2 kW	20 m	R88A-CAGB020S	R88A-CAGB020B
1,000-r/min Servomotors of 900 W	30 m	R88A-CAGB030S	R88A-CAGB030B
	40 m	R88A-CAGB040S	R88A-CAGB040B
	50 m	R88A-CAGB050S	R88A-CAGB050B
	3 m	R88A-CAGB003S	R88A-CAKF003B
	5 m	R88A-CAGB005S	R88A-CAKF005B
[400 V]	10 m	R88A-CAGB010S	R88A-CAKF010B
3,000-r/min Servomotors of 750 W to 2 kW	15 m	R88A-CAGB015S	R88A-CAKF015B
2,000-r/min Servomotors of 400 W to 2 kW 1,000-r/min Servomotors of 900 W	20 m	R88A-CAGB020S	R88A-CAKF020B
1,000-1/IIIII Servoinotors of 900 W	30 m	R88A-CAGB030S	R88A-CAKF030B
	40 m	R88A-CAGB040S	R88A-CAKF040B
	50 m	R88A-CAGB050S	R88A-CAKF050B
	3 m	R88A-CAGD003S	R88A-CAGD003B
	5 m	R88A-CAGD005S	R88A-CAGD005B
[200 V] [400 V]	10 m	R88A-CAGD010S	R88A-CAGD010B
3,000-r/min Servomotors of 3 to 5 kW	15 m	R88A-CAGD015S	R88A-CAGD015B
2,000-r/min Servomotors of 3 to 5 kW 1,000-r/min Servomotors of 2 to 4.5 kW	20 m	R88A-CAGD020S	R88A-CAGD020B
1,000-1/IIIII Servoinotors of 2 to 4.5 kvv	30 m	R88A-CAGD030S	R88A-CAGD030B
	40 m	R88A-CAGD040S	R88A-CAGD040B
	50 m	R88A-CAGD050S	R88A-CAGD050B
	3 m	R88A-CAGE003S	
	5 m	R88A-CAGE005S	
	10 m	R88A-CAGE010S	
[200 V] [400 V] 1,500-r/min Servomotors of 7.5 kW	15 m	R88A-CAGE015S	
1,000-r/min Servomotors of 6 kW	20 m	R88A-CAGE020S	
	30 m	R88A-CAGE030S	
	40 m	R88A-CAGE040S	
	50 m	R88A-CAGE050S	

Note: 1. Different connectors are used for the motor power and the brake on 100-V and 200-V, 3,000-r/min Servomotors of 50 to 750 W and Servomotors of 6 to 15 kW. When using a Servomotor with a brake, two cables are required: a Power Cable without Brake and a Brake Cable.

^{2.} For non-flexible power cables for Servomotors of 11 or 15 kW, refer to the G5 series USER'S MANUAL and make your own cable. Confirm the Manual No. that is listed in Related Manuals.

Brake Cable

Specifications		Non-flexible Cables	
		Model	
	3 m	R88A-CAKA003B	
	5 m	R88A-CAKA005B	
[100 V][200 V]	10 m	R88A-CAKA010B	
3,000-r/min	15 m	R88A-CAKA015B	
Servomotors of	20 m	R88A-CAKA020B	
50 to 750 W	30 m	R88A-CAKA030B	
	40 m	R88A-CAKA040B	
	50 m	R88A-CAKA050B	
	3 m	R88A-CAGE003B	
[200 V][400 V]	5 m	R88A-CAGE005B	
1,500-r/min	10 m	R88A-CAGE010B	
Servomotors of 7.5 to 15 kW	15 m	R88A-CAGE015B	
1,000-r/min	20 m	R88A-CAGE020B	
Servomotors of	30 m	R88A-CAGE030B	
6 kW	40 m	R88A-CAGE040B	
	50 m	R88A-CAGE050B	

Encoder Cable

Specifications		Non-flexible Cables	
		Model	
	3 m	R88A-CRKA003C	
	5 m	R88A-CRKA005C	
[100 V/200 V]	10 m	R88A-CRKA010C	
3,000-r/min	15 m	R88A-CRKA015C	
Servomotors of	20 m	R88A-CRKA020C	
50 to 750 W	30 m	R88A-CRKA030C	
	40 m	R88A-CRKA040C	
	50 m	R88A-CRKA050C	
[100 V and 200 V] 3.000-r/min Servomotors	3 m	R88A-CRKC003N	
	5 m	R88A-CRKC005N	
of 1.0 kW or more 2,000-r/min Servomotors	10 m	R88A-CRKC010N	
1,500-r/min Servomotors 1,000-r/min Servomotors	15 m	R88A-CRKC015N	
[400 V] 3,000-r/min Servomotors 2,000-r/min Servomotors	20 m	R88A-CRKC020N	
	30 m	R88A-CRKC030N	
1,500-r/min Servomotors 1,000-r/min Servomotors	40 m	R88A-CRKC040N	
1,000 1/111111 061 1011101013	50 m	R88A-CRKC050N	

<Flexible Cables>

Power cable

Specifications		Without brake	With brake
		Model	Model
	3 m	R88A-CAKA003SR	
	5 m	R88A-CAKA005SR	Note: There are separate connectors for
	10 m	R88A-CAKA010SR	power and brakes for 3,000-r/min
[100 V/200 V]	15 m	R88A-CAKA015SR	Servomotors of 50 to 750W. When a Servomotor with a brake is used, it is
3,000-r/min Servomotors of 50 to 750 W	20 m	R88A-CAKA020SR	necessary to use both a PowerCable
	30 m	R88A-CAKA030SR	for Servomotors without brakes and
	40 m	R88A-CAKA040SR	Power cable.
	50 m	R88A-CAKA050SR	
	3 m	R88A-CAGB003SR	R88A-CAGB003BR
	5 m	R88A-CAGB005SR	R88A-CAGB005BR
[200 V]	10 m	R88A-CAGB010SR	R88A-CAGB010BR
3,000-r/min Servomotors of 1 to 2 kW	15 m	R88A-CAGB015SR	R88A-CAGB015BR
2,000-r/min Servomotors of 1 to 2 kW 1,000-r/min Servomotors of 900 W	20 m	R88A-CAGB020SR	R88A-CAGB020BR
1,000-1/IIIII Servoinotors of 900 W	30 m	R88A-CAGB030SR	R88A-CAGB030BR
	40 m	R88A-CAGB040SR	R88A-CAGB040BR
	50 m	R88A-CAGB050SR	R88A-CAGB050BR
	3 m	R88A-CAGB003SR	R88A-CAKF003BR
	5 m	R88A-CAGB005SR	R88A-CAKF005BR
[400 V]	10 m	R88A-CAGB010SR	R88A-CAKF010BR
3,000-r/min Servomotors of 750 W to 2 kW	15 m	R88A-CAGB015SR	R88A-CAKF015BR
2,000-r/min Servomotors of 400 W to 2 kW 1,000-r/min Servomotors of 900 W	20 m	R88A-CAGB020SR	R88A-CAKF020BR
1,000-1/IIIII Servoinotors of 900 W	30 m	R88A-CAGB030SR	R88A-CAKF030BR
	40 m	R88A-CAGB040SR	R88A-CAKF040BR
	50 m	R88A-CAGB050SR	R88A-CAKF050BR
[200 V] [400 V] 3,000-r/min Servomotors of 3 to 5 kW	3 m	R88A-CAGD003SR	R88A-CAGD003BR
	5 m	R88A-CAGD005SR	R88A-CAGD005BR
	10 m	R88A-CAGD010SR	R88A-CAGD010BR
	15 m	R88A-CAGD015SR	R88A-CAGD015BR
2,000-r/min Servomotors of 3 to 5 kW 1,000-r/min Servomotors of 4.5 kW	20 m	R88A-CAGD020SR	R88A-CAGD020BR
1,000-1/111111 GELVOITIOLOIS OF 4.3 KW	30 m	R88A-CAGD030SR	R88A-CAGD030BR
	40 m	R88A-CAGD040SR	R88A-CAGD040BR
Note: 4 Different connectors are used for	50 m	R88A-CAGD050SR	R88A-CAGD050BR

Note: 1. Different connectors are used for the motor power and the brake on 100-V and 200-V, 3,000-r/min Servomotors of 50 to 750 W and Servomotors of 6 to 15 kW. When using a Servomotor with a brake, two cables are required: a Power Cable without Brake and a Brake Cable.

Note: 2. For flexible power cables for Servomotors of 11 to 15 kW, refer to the G5 series USER'S MANUAL and make your own cable.

For flexible power cables for Servomotors of 6 to 7.5 kW, refer to the G5 series USER'S MANUAL and make your own power cable.

Brake Cable

Brane Gabie			
Specifications		Flexible Cables	
		Model	
	3 m	R88A-CAKA003BR	
	5 m	R88A-CAKA005BR	
[100 V] [200 V]	10 m	R88A-CAKA010BR	
3,000-r/min	15 m	R88A-CAKA015BR	
Servomotors of	20 m	R88A-CAKA020BR	
50 to 750 W	30 m	R88A-CAKA030BR	
_	40 m	R88A-CAKA040BR	
	50 m	R88A-CAKA050BR	

Note: For flexible brake cables for Servomotors of 6 to 15 kW, refer to the G5 series USER'S MANUAL and make your own brake cable. Confirm the Manual No. that is listed in Related Manuals.

Encoder Cable

Specifications		Flexible Cables	
		Model	
	3 m	R88A-CRKA003CR	
[100 V/200 V]	5 m	R88A-CRKA005CR	
3,000-r/min Servomotors of	10 m	R88A-CRKA010CR	
50 to 750 W	15 m	R88A-CRKA015CR	
(for both absolute encoders and	20 m	R88A-CRKA020CR	
incremental	30 m	R88A-CRKA030CR	
encoders)	40 m	R88A-CRKA040CR	
	50 m	R88A-CRKA050CR	
	3 m	R88A-CRKC003NR	
[100 V and 200 V] 3,000-r/min Servomotors	5 m	R88A-CRKC005NR	
of 1.0 kW or more 2,000-r/min Servomotors	10 m	R88A-CRKC010NR	
1,500-r/min Servomotors 1,000-r/min Servomotors	15 m	R88A-CRKC015NR	
[400 V] 3,000-r/min Servomotors 2,000-r/min Servomotors	20 m	R88A-CRKC020NR	
	30 m	R88A-CRKC030NR	
1,500-r/min Servomotors 1,000-r/min Servomotors	40 m	R88A-CRKC040NR	
1,000 1,111111 001 1011101010	50 m	R88A-CRKC050NR	

Ordering Information

■ Cable/Connector

Absolute Encoder Battery Cable

Name	Length	model
Absolute Encoder Battery Cable (Battery not included)	0.3 m	R88A-CRGD0R3C
Absolute Encoder Battery Cable (One R88A-BAT01G Battery included)	0.3 m	R88A-CRGD0R3C-BS

Absolute Encoder Backup Battery

Specifications	Model
2.000 mA • h 3.6 V	R88A-BAT01G

Analog Monitor Cable

Name	Length	Model
Analog Monitor Cable	1 m	R88A-CMK001S

Servo Drive Connectors (common)

Name	Connects to	Model
Encoder Connector	CN2	R88A-CNW01R
External Scale Connector	CN4	R88A-CNK41L
safety bypass connector	CN8	R88A-CNK81S

Servo Drive Connectors

Name	Connects to	Drive type	Model
		General-purpose Input	R88A-CNU11C
Control I/O Connector	CN1	MECHATROLINK-II Communications EtherCAT Communications EtherCAT Communications Linear motor	R88A-CNW01C

Servomotor Connector

Name		Model
Name	Applicable Servomotor Capacity	Woder
	[100 V/200 V] 3,000 r/min (50 to 750 W)	R88A-CNK02R
Servomotor Connector for Encoder Cable	[100 V/200 V] 3,000 r/min (1 to 5 kW) 2,000r/min,1,000r/min [400 V] 3,000 r/min, 2,000 r/min, 1,000 r/min	R88A-CNK04R
Power Cable Connector	(750 W max.)	R88A-CNK11A
Brake Cable Connector	(750 W max.)	R88A-CNK11B

External Encoder Cable

Name	Lengths	Model
Serial Communications Cable	10 m	R88A-CRKE010SR

■ Control Cables

Control Cables (for Connector Terminal Block/CN1)

Name		Model		
Name		Specifications		Wodei
	General-nur	General-purpose Input		XW2Z-100J-B24
Connector Terminal Block Cables	Gerierai-pui	pose input	Length 2.0 m	XW2Z-200J-B24
Connector Terminal Block Cables	MECHATRO	DLINK-II Communications	Length 1.0 m	XW2Z-100J-B34
	EtherCAT C	ommunications	Length 2.0 m	XW2Z-200J-B34
	General- purpose Input	Conversion Unit for General-purpose Controllers (M3 screws)	Through type	XW2B-50G4
		Conversion Unit for General-purpose Controllers (M3.5 screws)	Through type	XW2B-50G5
Connector Terminal Block Conversion		Conversion Unit for General-purpose Controllers (M3 screws)	Slim type	XW2D-50G6
Unit	MECHATR OLINK-II	Conversion Unit for General-purpose Controllers (M3 screws)	Through type	XW2B-20G4
	Communic ations EtherCAT Communic ations	Conversion Unit for General-purpose Controllers (M3.5 screws)	Through type	XW2B-20G5
		Communic Co	Conversion Unit for General-purpose Controllers (M3 screws)	Slim type

● General-purpose Inputs (Analog input/Pulse train input type) Connection Cables (for CN1)

Specif	fications	The number	Length	Model
Name	Unit	of axes		Wodei
			1 m	XW2Z-100J-G9
		for 1 axis	5 m	XW2Z-500J-G9
Position Control Unit (High-speed type)	CJ1W-NC234/434		10 m	XW2Z-10MJ-G9
for Line-driver output	C01VV-NC254/454		1 m	XW2Z-100J-G1
		for 2 axis	5 m	XW2Z-500J-G1
			10 m	XW2Z-10MJ-G1
	CJ1W-NC214/NC414	for 1 axis	1 m	XW2Z-100J-G13
Position Control Unit (High-speed type)		ior i axis	3 m	XW2Z-300J-G13
for Open collector output		for 2 axis	1 m	XW2Z-100J-G5
			3 m	XW2Z-300J-G5
	CS1W-MC221 (-V1)	for 1 axis	1 m	R88A-CPG001M1
			2 m	R88A-CPG002M1
			3 m	R88A-CPG003M1
Control Cables			5 m	R88A-CPG005M1
for Motion Control Unit	CS1W-MC421 (-V1)		1 m	R88A-CPG001M2
		for 2 axis	2 m	R88A-CPG002M2
		IUI Z axis	3 m	R88A-CPG003M2
			5 m	R88A-CPG005M2
General-purpose Control Cables with	Cables for General-purpose Controllers		1 m	R88A-CPG001S
Connector on One End	Cables for General-purpose Controllers	_	2 m	R88A-CPG002S

Device for External Signal Connection / Connecting Cables (for CJ1W-NC□□4)

N	ame	Specifications		Model
Connection Cables Terminal Block Cables		Length 0.5 m	XW2Z-C50X	
	Normal wiring	Length 1.0 m	XW2Z-100X	
		Length 2.0 m	XW2Z-200X	
		Length 3.0 m	XW2Z-300X	
			Length 5.0 m	XW2Z-500X
		Length 10.0 m	XW2Z-010X	
	Connector	20 pin M2.4 screw Terminal Block type	Through type	XW2B-20G4
Terminal Block Conversion Unit	20 pin M3.5 screw Terminal Block type	Through type	XW2B-20G5	
	20 pin M3 screw Terminal Block type	Slim type	XW2D-20G6	

Servo Relay Units (for CN1)

Specifications	The number of axes	Model
Position Control Unit: For CJ1W-NC113/NC133 For CS1W-NC113/NC133 For C200HW-NC113	for 1 axis	XW2B-20J6-1B
Position Control Unit: For CJ1W-NC213/NC233/NC413/NC433 For CS1W-NC213/NC233/NC413/NC433 For C200HW-NC213/NC413	for 2 axis	XW2B-40J6-2B
For CJ2M-CPU31/CPU32/CPU33/CPU34/CPU35	for 1 axis	XW2B-20J6-8A
For CJ2M-CPU11/CPU12/CPU13/CPU14/CPU15	for 2 axis	XW2B-40J6-9A
For FQM1-MMA22 (Analog output) For FQM1-MMP22 (Pulse train output)	for 2 axis	XW2B-80J7-12A

Servo Relay Unit cable (for Servo Drive/CN1)

Specifications	Length	Model
Position Control Unit: For CJ1W-NC□□3□	1 m	XW2Z-100J-B25
For CS1W/C200HW-NC□□□ (XW2B-20J6-1B, XW2B-40J6-2B)	2 m	XW2Z-200J-B25
For CJ2M-CPU31/CPU32/CPU33/CPU34/CPU35	1 m	XW2Z-100J-B31
For CJ2M-CPU11/CPU12/CPU13/CPU14/CPU15 (XW2B-20J6-8A, XW2B-40J6-9A)	2 m	XW2Z-200J-B31
For FQM1-MMA22 (Analog output)	1 m	XW2Z-100J-B27
(XW2B-80J7-12A)	2 m	XW2Z-200J-B27
For FQM1-MMP22 (Pulse train output)	1 m	XW2Z-100J-B26
(XW2B-80J7-12A)	2 m	XW2Z-200J-B26

Note: You cannot use a Servo Relay Unit Cable for line-receiver inputs (+CWLD: CN1 pin 44, -CWLD: CN1 pin 45, +CCWLD: CN1 pin 46, -CCWLD: CN1 pin 47).

Use a General-purpose Control Cable and wire the connector to match the controller.

Servo Relay Unit cable (Position Control Unit)

Specifications		The number of axes	Length	Model
CJ1W line-driver output type		for 1 axis	0.5 m	XW2Z-050J-A18
For CJ1W-NC133 (XW2B-20J6-1B)		IOI I axis	1 m	XW2Z-100J-A18
CJ1W line-driver output type		for 2 axis	0.5 m	XW2Z-050J-A19
For CJ1W-NC233/NC433 (XW2B-40J6	-2B)	IOI Z AXIS	1 m	XW2Z-100J-A19
CS1W line-driver output type		for 1 axis	0.5 m	XW2Z-050J-A10
For CS1W-NC133 (XW2B-20J6-1B)		IOI I AXIS	1 m	XW2Z-100J-A10
CS1W line-driver output type		for 2 axis	0.5 m	XW2Z-050J-A11
For CS1W-NC233/NC433 (XW2B-40J6	6-2B)	TOT E UNIO	1 m	XW2Z-100J-A11
CJ1W open collector output type		for 1 axis	0.5 m	XW2Z-050J-A14
For CJ1W-NC113 (XW2B-20J6-1B)		TOT T UNIO	1 m	XW2Z-100J-A14
CJ1W open collector output type		for 2 axis	0.5 m	XW2Z-050J-A15
For CJ1W-NC213/NC413 (XW2B-40J6	-2B)	101 2 4313	1 m	XW2Z-100J-A15
CS1W/C200HW open collector output t For CS1W-NC113	уре	for 1 axis	0.5 m	XW2Z-050J-A6
For C200HW-NC113 (XW2B-20J6-1B)		ioi i axio	1 m	XW2Z-100J-A6
CS1W/C200HW open collector output type For CS1W-NC213/NC413 For C200HW-NC213/NC413 (XW2B-40J6-2B)		for 2 axis	0.5 m	XW2Z-050J-A7
		101 2 4310	1 m	XW2Z-100J-A7
CJ1M open collector output type			0.5 m	XW2Z-050J-A33
For CJ2M-CPU31/CPU32/CPU33/CPU For CJ2M-CPU11/CPU12/CPU13/CPU XW2B-20J6-8A, XW2B-40J6-9A)		for 1 axis	1 m	XW2Z-100J-A33
	General-		0.5 m	XW2Z-050J-A28
	purpose I/O	for 2 axis	1 m	XW2Z-100J-A28
For FQM1-MMA22 (Analog output)	(26 pin)		2 m	XW2Z-200J-A28
XW2B-80J7-12A)	Chariel I/O		0.5 m	XW2Z-050J-A31
	Special I/O (40 pin)	for 2 axis	1 m	XW2Z-100J-A31
	(40 piii)		2 m	XW2Z-200J-A31
	General-		0.5 m	XW2Z-050J-A28
	purpose I/O	for 2 axis	1 m	XW2Z-100J-A28
For FQM1-MMP22 (Pulse train output)	(26 pin)	2 m XW2Z-20	XW2Z-200J-A28	
(XW2B-80J7-12A)	0		0.5 m	XW2Z-050J-A30
	Special I/O (40 pin)	for 2 axis	1 m	XW2Z-100J-A30
	(40 piii)		2 m	XW2Z-200J-A30

■ Communication Cables

MECHATROLINK-II Communications

MECHATROLINK-related Devices and Cables (Manufactured by Yaskawa Corporation)

Name			Model	Yaskawa model number
Name		Length	(OMRON model number)	raskawa model number
		0.5 m	FNY-W6002-A5	JEPMC-W6002-A5-E
MECHATROLINK-II Cables (without ring core and USB connector on b	oth anda)	1.0 m	FNY-W6002-01	JEPMC-W6002-01-E
* Can be connected to R88D-GN and R88		3.0 m	FNY-W6002-03	JEPMC-W6002-03-E
4 can be connected to riceb are and riceb face only.		5.0 m	FNY-W6002-05	JEPMC-W6002-05-E
		0.5 m	FNY-W6003-A5	JEPMC-W6003-A5
		1.0 m	FNY-W6003-01	JEPMC-W6003-01
MEGUATROUNIKUROLU		3.0 m	FNY-W6003-03	JEPMC-W6003-03
MECHATROLINK-II Cables (with ring core and USB connector on both	ends)	5.0 m	FNY-W6003-05	JEPMC-W6003-05
(Marring core and cop connector on boar	orido)	10.0 m	FNY-W6003-10	JEPMC-W6003-10
		20.0 m	FNY-W6003-20	JEPMC-W6003-20
		30.0 m	FNY-W6003-30	JEPMC-W6003-30
MECHATROLINK-II Terminating Resistor	Terminating resistance		FNY-W6022	JEPMC-W6022
MECHATROLINK-II Repeater	Communication	ons Repeater	FNY-REP2000	JEPMC-REP2000

MECHATROLINK-related Devices and Cables are manufactured by Yaskawa Corporation, but they can be ordered directly from OMRON using the OMRON model numbers. (Yaskawa-brand products will be delivered even when they are ordered from OMRON.)

Recommended EtherCAT Communications Cables

Use Straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT.

Cabel with Connectors

Wire Gauge and Number of Pairs: AWG22, 2-pair Cable

Item	Appearance	Recommended manufacturer	Cable length(m)	Model
			0.3	XS5W-T421-AMD-K
			0.5	XS5W-T421-BMD-K
Cable with Connectors on Both Ends	** 6	OMRON	1	XS5W-T421-CMD-K
(RJ45/RJ45)			2	XS5W-T421-DMD-K
			5	XS5W-T421-GMD-K
			10	XS5W-T421-JMD-K
	-0	OMRON	0.3	XS5W-T421-AMC-K
			0.5	XS5W-T421-BMC-K
Cable with Connectors on Both Ends			1	XS5W-T421-CMC-K
(M12/RJ45)			2	XS5W-T421-DMC-K
			5	XS5W-T421-GMC-K
			10	XS5W-T421-JMC-K

Note: The cable length 0.3, 0.5, 1, 2, 3, 5, 10 and 15m are available. For details, refer to Cat.No.G019.

Cables / Connectors

Wire Gauge and Number of Pairs: AWG24, 4-pair Cable

Item	Appearance	Recommended manufacturer	Model
Cables	-	Hitachi Cable, Ltd.	NETSTAR-C5E SAB * 0.5 x 4P
	-	Kuramo Electric Co.	KETH-SB *
	-	SWCC Showa Cable Systems Co.	FAE-5004 *
RJ45 Connectors	ı	Panduit Corporation	MPS588 *

^{*} We recommend you to use above cable and connector together.

Wire Gauge and Number of Pairs: AWG22, 2-pair Cable

Item	Appearance	Recommended manufacturer	Model
Cables	-	Kuramo Electric Co.	KETH-PSB-OMR *
RJ45 Assembly Connector		OMRON	XS6G-T421-1 *

 $\ensuremath{\bigstar}$ We recommend you to use above cable and connector together.

Note: Connect both ends of cable shielded wires to the connector hoods.

■ Peripheral Devices (External Regeneration Resistors, Reactors, Mounting Brackets) External Regeneration Resistors

Specifications	Model
80 W 50 Ω	R88A-RR08050S
80 W 100 Ω	R88A-RR080100S
220 W 47 Ω	R88A-RR22047S1
500 W 20 Ω	R88A-RR50020S

Reactors

	Specifications				
General-purpose Inputs	MECHATROLINK-II Communications	EtherCAT Communications	Linear Motor with built-in EtherCAT communications	Model	
R88D-KTA5L/-KT01H (For single-phase input)	R88D-KNA5L-ML2/-KN01H-ML2 (For single-phase input)	R88D-KNA5L-ECT/-KN01H-ECT (For single-phase input)	R88D-KN01H-ECT-L (For single-phase input)	3G3AX-DL2002	
R88D-KT01L/-KT02H (For single-phase input)	R88D-KN01L-ML2/-KN02H-ML2 (For single-phase input)	R88D-KN01L-ECT/-KN02H-ECT (For single-phase input)	R88D-KN01L-ECT-L/-KN02H-ECT-L (For single-phase input)	3G3AX-DL2004	
R88D-KT02L/-KT04H (For single-phase input)	R88D-KN02L-ML2/-KN04H-ML2 (For single-phase input)	R88D-KN02L-ECT/-KN04H-ECT (For single-phase input)	R88D-KN02L-ECT-L/-KN04H-ECT-L (For single-phase input)	3G3AX-DL2007	
R88D-KT04L/-KT08H/ -KT10H (For single-phase input)	R88D-KN04L-ML2/-KN08H-ML2/ -KN10H-ML2 (For single-phase input)	R88D-KN04L-ECT/-KN08H-ECT/ -KN10H-ECT (For single-phase input)	R88D-KN04L-ECT-L/-KN08H-ECT-L/ -KN10H-ECT-L (For single-phase input)	3G3AX-DL2015	
R88D-KT15H (For single-phase input)	R88D-KN15H-ML2 (For single-phase input)	R88D-KN15H-ECT (For single-phase input)	R88D-KN15H-ECT-L (For single-phase input)	3G3AX-DL2022	
R88D-KT01H/-KT02H/ -KT04H/-KT08H/ -KT10H/-KT15H (For three-phase input)	R88D-KN01H-ML2/-KN02H-ML2/ -KN04H-ML2/-KN08H-ML2/ -KN10H-ML2/-KN15H-ML2 (For three-phase input)	R88D-KN01H-ECT/-KN02H-ECT/ -KN04H-ECT/KN08H-ECT/ -KN10H-ECT/-KN15H-ECT (For three-phase input)	R88D-KN01H-ECT-L/-KN02H-ECT-L/ -KN04H-ECT-L/-KN08H-ECT-L/ -KN10H-ECT-L/-KN15H-ECT-L (For three-phase input)	3G3AX-AL2025	
R88D-KT20H/-KT30H	R88D-KN20H-ML2/-KN30H-ML2	R88D-KN20H-ECT/-KN30H-ECT	-	3G3AX-AL2055	
R88D-KT50H	R88D-KN50H-ML2	R88D-KN50H-ECT	-	3G3AX-AL2110	
R88D-KT06F/-KT10F/-KT15F	R88D-KN06F-ML2/-KN10F-ML2/ -KN15F-ML2	R88D-KN06F-ECT/-KN10F-ECT/ -KN15F-ECT	R88D-KN06F-ECT-L/-KN10F-ECT-L/ -KN15F-ECT-L	3G3AX-AL4025	
R88D-KT20F/-KT30F	R88D-KN20F-ML2/-KN30F-ML2	R88D-KN20F-ECT/-KN30F-ECT	R88D-KN20F-ECT-L/-KN30F-ECT-L	3G3AX-AL4055	
R88D-KT50F	R88D-KN50F-ML2	R88D-KN50F-ECT	-	3G3AX-AL4110	
R88D-KT75H/-KT150F	_	R88D-KT75H-ECT/-KT150F-ECT	_	3G3AX-AL4220	

Mounting Brackets (L Brackets for Rack Mounting)

Specifications				
General-purpose Inputs	MECHATROLINK-II Communications	EtherCAT Communications	Linear Motor with built-in EtherCAT communications	Model
R88D-KTA5L/-KT01L/ -KT01H/-KT02H	R88D-KNA5L-ML2/-KN01L-ML2/ -KN01H-ML2/-KN02H-ML2	R88D-KNA5L-ECT/-KN01L-ECT/ -KN01H-ECT/-KN02H-ECT	R88D-KN01L-ECT-L/-KN01H-ECT-L/ -KN02H-ECT-L	R88A-TK01K
R88D-KT02L/-KT04H	R88D-KN02L-ML2/-KN04H-ML2	R88D-KN02L-ECT/-KN04H-ECT	R88D-KN02L-ECT-L/-KN04H-ECT-L	R88A-TK02K
R88D-KT04L/-KT08H	R88D-KN04L-ML2/-KN08H-ML2	R88D-KN04L-ECT/-KN08H-ECT	R88D-KN04L-ECT-L/-KN08H-ECT-L	R88A-TK03K
R88D-KT10H/KT15H/ -KT06F/-KT10F/-KT15F	R88D-KN10H-ML2/-KN15H-ML2/ -KN06F-ML2/-KN10F-ML2/ -KN15F-ML2	R88D-KN10H-ECT/-KN15H-ECT/ -KN06F-ECT/-KN10F-ECT/ -KN15F-ECT	R88D-KN10H-ECT-L/-KN15H-ECT-L/ -KN06F-ECT-L/-KN10F-ECT-L/ -KN15F-ECT-L	R88A-TK04K

Note: Mounting brackets are provided with Servo Drives of 2 to 15 kW.

■ Software

How to Select Required Support Software for Your Controller

The required Support Software depends on the Controller to connect. Please check the following table when purchasing the Support Software.

Item	Omron PLC System	Omron Machine Automation Controller System
Controller	CS, CJ, CP, and other series	NJ-series
AC Servomotor/Drivers	G5-series • EtherCAT Communications • EtherCAT Communications Linear Motor • General-purpose input type(PulseTrain or Analog inputs) • MECHATROLINK-II Communications	G5-series • EtherCAT Communications (Unit version 2.1 or later recommended) • EtherCAT Communications Linear Motor
Software	FA Intergrated Tool Package CX-One	Automation Software Sysmac Studio

■ FA Integrated Tool Package CX-One

Product name	Specifications	Number of licenses	Media	Model	Standards	
FA Integrated Tool Package CX-One Ver. 4.□	The CX-One is a comprehensive software package that integrates Support Software for OMRON PLCs and components. CX-One runs on following OS. OS: Windows XP (Service Pack 3 or higher), Vista or 7 Note: Except for Windows XP 64-bit version. CX-One Version.4. includes CX-Drive Ver.2.	1 license *1	DVD *2	CXONE-AL01D-V4	-	

^{*1.} Multi licenses are available for the CX-One (3, 10, 30, or 50 licenses). ***2.** The CX-One is also available on CD (CXONE-AL□□C-V4).

■ Automation Software Sysmac Studio

Please purchase a DVD and required number of licenses the first time you purchase the Sysmac Studio. DVDs and licenses are available individually. Each model of licenses does not include any DVD.

Product name	Specifications	Number of licenses Media		Model	Standards
Sysmac Studio	The Sysmac Studio provides an integrated development environment to set up, program, debug, and maintain NJ-series Controllers and other Machine Automation Controllers, as well as EtherCAT slaves. Sysmac Studio runs on the following OS. Windows XP (Service Pack 3 or higher, 32-bit version)/ Vista (32-bit version) / 7 (32-bit/64-bit version)	- (Media only)	DVD	SYSMAC-SE200D	-
Standard Edition Ver.1.□□	The Sysmac Studio Standard Edition DVD includes Support Software to set up EtherNet/IP Units, DeviceNet slaves, Serial Communications Units, and Support Software for creating screens on HMIs (CX-Designer). For details, refer to the Sysmac Integrated Catalogue (P072).	1 license *	-	SYSMAC-SE201L	-

^{*}Multi licenses are available for the Sysmac Studio (3, 10, 30, or 50 licenses).

Combination table

AC Servo Drive and Servomotor Combinations (3,000 r/min, 2,000 r/min, 1,500r/min, 1,000 r/min)

<Cylinder Type>

● 3,000-r/min servomotors

Power Supply	Servo Drive Model Numbers			Servomotor Model Numbers		
Voltage	General-purpose Inputs	MECHATROLINK-II	EtherCAT	Output	With incremental encoder	With absolute encoder
	R88D-KTA5L	R88D-KNA5L-ML2	R88D-KNA5L-ECT	50 W	R88M-K05030H-□	R88M-K05030T-□
Single-phase	R88D-KT01L	R88D-KN01L-ML2	R88D-KN01L-ECT	100 W	R88M-K10030L-□	R88M-K10030S-□
100 to 120 VAC	R88D-KT02L	R88D-KN02L-ML2	R88D-KN02L-ECT	200 W	R88M-K20030L-□	R88M-K20030S-□
	R88D-KT04L	R88D-KN04L-ML2	R88D-KN04L-ECT	400 W	R88M-K40030L-□	R88M-K40030S-□
	R88D-KT01H *	R88D-KN01H-ML2 *	R88D-KN01H-ECT *	50 W	R88M-K05030H-□ *	R88M-K05030T-□ *
	R88D-KT01H	R88D-KN01H-ML2	R88D-KN01H-ECT	100 W	R88M-K10030H-□	R88M-K10030T-□
Single-phase/	R88D-KT02H	R88D-KN02H-ML2	R88D-KN02H-ECT	200 W	R88M-K20030H-□	R88M-K20030T-□
three-phase	R88D-KT04H	R88D-KN04H-ML2	R88D-KN04H-ECT	400 W	R88M-K40030H-□	R88M-K40030T-□
200 to 240 VAC	R88D-KT08H	R88D-KN08H-ML2	R88D-KN08H-ECT	750 W	R88M-K75030H-□	R88M-K75030T-□
	R88D-KT15H *	R88D-KN15H-ML2 *	R88D-KN15H-ECT *	1 kW	R88M-K1K030H-□ *	R88M-K1K030T-□ *
	R88D-KT15H	R88D-KN15H-ML2	R88D-KN15H-ECT	1.5 kW	R88M-K1K530H-□	R88M-K1K530T-□
	R88D-KT20H	R88D-KN20H-ML2	R88D-KN20H-ECT	2 kW	R88M-K2K030H-□	R88M-K2K030T-□
Three-phase	R88D-KT30H	R88D-KN30H-ML2	R88D-KN30H-ECT	3 kW	R88M-K3K030H-□	R88M-K3K030T-□
200 to 240 VAC	R88D-KT50H	R88D-KN50H-ML2	R88D-KN50H-ECT *	4 kW	R88M-K4K030H-□	R88M-K4K030T-□
	R88D-KT50H	R88D-KN50H-ML2	R88D-KN50H-ECT	5 kW	R88M-K5K030H-□	R88M-K5K030T-□
	R88D-KT10F	R88D-KN10F-ML2	R88D-KN10F-ECT *	750 W	R88M-K75030F-□	R88M-K75030C-□
	R88D-KT15F *	R88D-KN15F-ML2 *	R88D-KN15F-ECT *	1 kW	R88M-K1K030F-□ *	R88M-K1K030C-□ *
	R88D-KT15F	R88D-KN15F-ML2	R88D-KN15F-ECT	1.5 kW	R88M-K1K530F-□	R88M-K1K530C-□
Three-phase 400 to 480 VAC	R88D-KT20F	R88D-KN20F-ML2	R88D-KN20F-ECT	2 kW	R88M-K2K030F-□	R88M-K2K030C-□
400 10 400 770	R88D-KT30F	R88D-KN30F-ML2	R88D-KN30F-ECT	3 kW	R88M-K3K030F-□	R88M-K3K030C-□
	R88D-KT50F	R88D-KN50F-ML2	R88D-KN50F-ECT *	4 kW	R88M-K4K030F-□	R88M-K4K030C-□
	R88D-KT50F	R88D-KN50F-ML2	R88D-KN50F-ECT	5 kW	R88M-K5K030F-□	R88M-K5K030C-□

● 1,500r/min, 2,000-r/min servomotors

Power Supply Voltage		Servo Drive Model Num	bers		Servomotor Model I	Numbers
	General-purpose Inputs	MECHATROLINK-II	EtherCAT	Output	With incremental encoder	With absolute encoder
Single-phase/	R88D-KT10H	R88D-KN10H-ML2	R88D-KN10H-ECT	1 kW	R88M-K1K020H-□	R88M-K1K020T-□
three-phase 200 to 240 VAC	R88D-KT15H	R88D-KN15H-ML2	R88D-KN15H-ECT	1.5 kW	R88M-K1K520H-□	R88M-K1K520T-□
	R88D-KT20H	R88D-KN20H-ML2	R88D-KN20H-ECT	2 kW	R88M-K2K020H-□	R88M-K2K020T-□
	R88D-KT30H	R88D-KN30H-ML2	R88D-KN30H-ECT	3 kW	R88M-K3K020H-□	R88M-K3K020T-□
	R88D-KT50H *	R88D-KN50H-ML2 *	R88D-KN50H-ECT *	4 kW	R88M-K4K020H-□ *	R88M-K4K020T-□ *
Three-phase 200 to 240 VAC	R88D-KT50H	R88D-KN50H-ML2	R88D-KN50H-ECT	5 kW	R88M-K5K020H-□	R88M-K5K020T-□
200 10 240 VAC	R88D-KT75H	_	R88D-KN75H-ECT	7.5 kW	_	R88M-K7K515T-□
	R88D-KT150H *	-	R88D-KN150H-ECT *	11 kW	-	R88M-K11K015T-□ \$
	R88D-KT150H	-	R88D-KN150H-ECT	15 kW	-	R88M-K15K015T-□
	R88D-KT06F	R88D-KN06F-ML2	R88D-KN06F-ECT*	400 W	R88M-K40020F-□	R88M-K40020C-□
	R88D-KT06F	R88D-KN06F-ML2	R88D-KN06F-ECT	600 W	R88M-K60020F-□	R88M-K60020C-□
	R88D-KT10F	R88D-KN10F-ML2	R88D-KN10F-ECT	1 kW	R88M-K1K020F-□	R88M-K1K020C-□
	R88D-KT15F	R88D-KN15F-ML2	R88D-KN15F-ECT	1.5 kW	R88M-K1K520F-□	R88M-K1K520C-□
	R88D-KT20F	R88D-KN20F-ML2	R88D-KN20F-ECT	2 kW	R88M-K2K020F-□	R88M-K2K020C-□
Three-phase 400 to 480 VAC	R88D-KT30F	R88D-KN30F-ML2	R88D-KN30F-ECT	3 kW	R88M-K3K020F-□	R88M-K3K020C-□
400 to 400 VAC	R88D-KT50F *	R88D-KN50F-ML2 *	R88D-KN50F-ECT *	4 kW	R88M-K4K020F-□ *	R88M-K4K020C-□ *
	R88D-KT50F	R88D-KN50F-ML2	R88D-KN50F-ECT	5 kW	R88M-K5K020F-□	R88M-K5K020C-□
	R88D-KT75F	-	R88D-KN75F-ECT	7.5 kW	-	RR88M-K7K515C-□
	R88D-KT150F *	-	R88D-KN150F-ECT *	11 kW	-	R88M-K11K015C-□ *
	R88D-KT150F	-	R88D-KN150F-ECT	15 kW	-	R88M-K15K015C-□

^{*} Please use the Servo Drive and Servomotor in this combination although their capacity is not same.

● 1,000-r/min servomotors

Power Supply Servo Drive Model I		Servo Drive Model Num	bers		Servomotor Model Numbers		
Voltage	General-purpose Inputs	MECHATROLINK-II	EtherCAT	Output	With incremental encoder	With absolute encoder	
Single-phase/ three-phase 200 to 240 VAC	R88D-KT15H *	R88D-KN15H-ML2 *	R88D-KN15H-ECT *	900 W	R88M-K90010H-□ *	R88M-K90010T-□ *	
	R88D-KT30H *	R88D-KN30H-ML2 *	R88D-KN30H-ECT *	2 kW	R88M-K2K010H-□ *	R88M-K2K010T-□ *	
Three-phase	R88D-KT50H *	R88D-KN50H-ML2 *	R88D-KN50H-ECT *	3 kW	R88M-K3K010H-□ *	R88M-K3K010T-□ *	
200 to 240 VAC	R88D-KT50H *	-	R88D-KN50H-ECT *	4.5 kW	-	R88M-K4K510T-□ *	
	R88D-KT75H *	-	R88D-KN75H-ECT *	6 kW	-	R88M-K6K010T-□ *	
	R88D-KT15F *	R88D-KN15F-ML2 *	R88D-KN15F-ECT *	900 W	R88M-K90010F-□ *	R88M-K90010C-□ *	
	R88D-KT30F *	R88D-KN30F-ML2 *	R88D-KN30F-ECT *	2 kW	R88M-K2K010F-□ *	R88M-K2K010C-□ *	
Three-phase 400 to 480 VAC	R88D-KT50F *	R88D-KN50F-ML2 *	R88D-KN50F-ECT *	3 kW	R88M-K3K010F-□ *	R88M-K3K010C-□ *	
	R88D-KT50F *	-	R88D-KN50F-ECT *	4.5 kW	-	R88M-K4K510C-□ *	
	R88D-KT75F *	-	R88D-KN75F-ECT *	6 kW	-	R88M-K6K010C-□ *	

^{*} Please use the Servo Drive and Servomotor in this combination although their capacity is not same.

AC Servomotor and Decelerator Combinations (3,000 r/min, 2,000 r/min, 1,000 r/min)

<Cylinder Type>

• 3,000-r/min servomotors

Motor model	1/5	1/11 (1/9 for flange size No.11)	1/21	1/33	1/45
R88M-K05030□	R88G-HPG11B05100B□ (Also used with R88M- K10030□)	R88G-HPG11B09050B (Gear ratio 1/9)	R88G-HPG14A21100B□ (Also used with R88M- K10030□)	R88G-HPG14A33050B□	R88G-HPG14A45050B
R88M-K10030□	R88G-HPG11B05100B	R88G-HPG14A11100B	R88G-HPG14A21100B□	R88G-HPG20A33100B□	R88G-HPG20A45100B
R88M-K20030□	R88G-HPG14A05200B	R88G-HPG14A11200B	R88G-HPG20A21200B	R88G-HPG20A33200B	R88G-HPG20A45200B
R88M-K40030□	R88G-HPG14A05400B□	R88G-HPG20A11400B	R88G-HPG20A21400B	R88G-HPG32A33400B□	R88G-HPG32A45400B
R88M-K75030H/T (200 V)	R88G-HPG20A05750B	R88G-HPG20A11750B	R88G-HPG32A21750B	R88G-HPG32A33750B	R88G-HPG32A45750B
R88M-K75030F/C (400 V)	R88G-HPG32A052K0B (Also used with R88M-K2K030)	R88G-HPG32A112K0B□ (Also used with R88M- K2K030□)	R88G-HPG32A211K5B (Also used with R88M-K1K5030)	R88G- HPG32A33600SB□ (Also used with R88M- K60020□)	R88G-HPG50A451K5B□ (Also used with R88M- K1K530□)
R88M-K1K030□	R88G-HPG32A052K0B□ (Also used with R88M- K2K030□)	R88G-HPG32A112K0B (Also used with R88M-K2K030)	R88G-HPG32A211K5B□ (Also used with R88M- K1K5030□)	R88G-HPG50A332K0B (Also used with R88M-K2K030)	R88G-HPG50A451K5B (Also used with R88M-K1K530)
R88M-K1K530□	R88G-HPG32A052K0B (Also used with R88M-K2K030)	R88G-HPG32A112K0B (Also used with R88M-K2K030)	R88G-HPG32A211K5B□	R88G-HPG50A332K0B (Also used with R88M-K2K030)	R88G-HPG50A451K5B
R88M-K2K030□	R88G-HPG32A052K0B□	R88G-HPG32A112K0B□	R88G-HPG50A212K0B□	R88G-HPG50A332K0B□	-
R88M-K3K030□	R88G-HPG32A053K0B□	R88G-HPG50A113K0B□	R88G-HPG50A213K0B□	-	-
R88M-K4K030□	R88G-HPG32A054K0B□	R88G-HPG50A115K0B (Also used with R88M-K5K030)	-	-	-
R88M-K5K030□	R88G-HPG50A055K0B□	R88G-HPG50A115K0B□	-	-	-

● 2,000-r/min servomotors

Motor model	1/5	1/11	1/21 (1/20 for flange size No.65)	1/33 (1/25 for flange size No.65)	1/45
R88M-K40020 (Only 400 V)	R88G-HPG32A052K0B (Also used with R88M-K2K030)	R88G-HPG32A112K0B (Also used with R88M-K2K030□)	R88G-HPG32A211K5B (Also used with R88M-K1K5030)	R88G- HPG32A33600SB□ (Also used with R88M- K60020□)	R88G- HPG32A45400SB□
R88M-K60020□ (Only 400 V)	R88G-HPG32A052K0B (Also used with R88M-K2K030)	R88G-HPG32A112K0B (Also used with R88M-K2K030□)	R88G-HPG32A211K5B (Also used with R88M-K1K5030)	R88G- HPG32A33600SB□	R88G-HPG50A451K5B (R88M-K1K530)
R88M-K1K020□	R88G-HPG32A053K0B (Also used with R88M-K3K030)	R88G- HPG32A112K0SB□ (Also used with R88M- K2K020□)	R88G- HPG32A211K0SB□	R88G- HPG50A332K0SB□ (Also used with R88M- K2K020□)	R88G- HPG50A451K0SB□
R88M-K1K520□	R88G-HPG32A053K0B (Also used with R88M-K3K030)	R88G- HPG32A112K0SB□ (Also used with R88M- K2K020□)	R88G-HPG50A213K0B (Also used with R88M-K3K030□)	R88G- HPG50A332K0SB□ (Also used with R88M- K2K020□)	-
R88M-K2K020□	R88G-HPG32A053K0B□ (Also used with R88M- K3K030□)	R88G- HPG32A112K0SB□	R88G-HPG50A213K0B (Also used with R88M-K3K030□)	R88G- HPG50A332K0SB□	-
R88M-K3K020□	R88G-HPG32A054K0B (Also used with R88M-K4K030)	R88G-HPG50A115K0B (Also used with R88M-K5K030)	R88G- HPG50A213K0SB□	R88G- HPG65A253K0SB□	-
R88M-K4K020□	R88G- HPG50A055K0SB□ (Also used with R88M- K5K020□)	R88G- HPG50A115K0SB□ (Also used with R88M- K3K030□)	R88G- HPG65A205K0SB□ (Also used with R88M- K3K030□)	R88G- HPG65A255K0SB□ (Also used with R88M- K5K020□)	-
R88M-K5K020□	R88G- HPG50A055K0SB□	R88G- HPG50A115K0SB□	R88G- HPG65A205K0SB□	R88G- HPG65A255K0SB□	-

● 1,000-r/min servomotors

Motor model	1/5	1/11	1/21 (1/20 for flange size No.65)	1/33 (1/25 for flange size No.65)
R88M-K90010□	R88G-HPG32A05900TB□	R88G-HPG32A11900TB□	R88G-HPG50A21900TB□	R88G-HPG50A33900TB□
R88M-K2K010□	R88G-HPG32A052K0TB□	R88G-HPG50A112K0TB□	R88G-HPG50A212K0TB (Also used with R88M- K5K020)	R88G-HPG65A255K0SB (Also used with R88M-K5K020)
R88M-K3K010□	R88G-HPG50A055K0SB (Also used with R88M-K5K020)	R88G-HPG50A115K0SB (Also used with R88M- K5K020)	R88G-HPG65A205K0SB (Also used with R88M- K5K020)	R88G-HPG65A255K0SB (Also used with R88M-K5K020)

Linear Motor and AC Servo Drive Linear Motor Type Combinations

● Iron-core Linear Motor type

Linear Motor Model Numbers	Power Supply Voltage (V)	Servo Drive Model Numbers	Maximum speed (m/s)
	100	R88D-KN01L-ECT-L	2.5
R88L-EC-FW-0303-ANPC	200	R88D-KN02H-ECT-L	5
	400	R88D-KN06F-ECT-L	10
	100	R88D-KN02L-ECT-L	2.5
R88L-EC-FW-0306-ANPC	200	R88D-KN04H-ECT-L	5
	400	R88D-KN10F-ECT-L	10
	100	R88D-KN04L-ECT-L	2
R88L-EC-FW-0606-ANPC	200	R88D-KN08H-ECT-L	4
	400	R88D-KN15F-ECT-L	8
R88L-EC-FW-0609-ANPC	200	R88D-KN10H-ECT-L	4
NOOL-EC-FW-0009-AINFC	400	R88D-KN20F-ECT-L	8
R88L-EC-FW-0612-ANPC	200	R88D-KN15H-ECT-L	4
HOOL-LO-I W-0012-ANFO	400	R88D-KN30F-ECT-L	8
R88L-EC-FW-1112-ANPC	200	R88D-KN15H-ECT-L	2
	400	R88D-KN30F-ECT-L	4
DOOL EC EW 1115 ANDC	200	R88D-KN15H-ECT-L	2
R88L-EC-FW-1115-ANPC	400	R88D-KN30F-ECT-L	4

● Ironless Linear Motor type

Linear Motor Model Numbers	Power Supply Voltage (V)	Servo Drive Model Numbers	Maximum speed (m/s)
R88L-EC-GW-0303-ANPS	100	R88D-KN01L-ECT-L	8
HOOL-EC-GW-0303-ANF3	200	R88D-KN02H-ECT-L	16
R88L-EC-GW-0306-ANPS	100	R88D-KN04L-ECT-L	8
NOOL-EC-GW-0300-ANF3	200	R88D-KN08H-ECT-L	16
R88L-EC-GW-0309-ANPS	200	R88D-KN10H-ECT-L	16
R88L-EC-GW-0503-ANPS	100	R88D-KN01L-ECT-L	2.2
NOOL-EC-GW-0303-ANF3	200	R88D-KN02H-ECT-L	4.4
R88L-EC-GW-0506-ANPS	100	R88D-KN02L-ECT-L	2.2
NOOL-EC-GW-0300-ANF3	200	R88D-KN04H-ECT-L	4.4
R88L-EC-GW-0509-ANPS	100	R88D-KN04L-ECT-L	2.2
H86L-EC-GW-0309-ANPS	200	R88D-KN08H-ECT-L	4.4
R88L-EC-GW-0703-ANPS	100	R88D-KN02L-ECT-L	1.2
R88L-EC-GW-0703-ANPS	200	R88D-KN04H-ECT-L	2.4
R88L-EC-GW-0706-ANPS	100	R88D-KN04L-ECT-L	1.2
	200	R88D-KN08H-ECT-L	2.4
R88L-EC-GW-0709-ANPS	200	R88D-KN10H-ECT-L	2.4

Note: The maximum operation speed is limited by considering the guide mechanism, encoder, and other aspects. If it is 5 m/s or higher, please consult with your OMRON representative.

Controller Combinations

Position Control unit ,Servo Relay Units and Cables

Select the Servo Relay Unit and Cable according to the model number of the Position Control Unit being used.

Position Control Unit			Se	ervo Relay Unit	Servo Drive Cable	
CS1W-NC113		VW07 1 40		WOD 00 IC 4D		
C200HW-NC113		XW2Z-□□□J-A6	^	(W2B-20J6-1B		
CS1W-NC213						
CS1W-NC413		XW2Z-□□□J-A7		(W2B-40J6-2B		
C200HW-NC213		XVVZZ-LILIJ-A7	^	WZB-40J0-ZB		
C200HW-NC413						
CS1W-NC133)	KW2Z-□□□J-A10	×	W2B-20J6-1B		
CS1W-NC233	,	KW2Z-□□□J-A11		(W2B-40J6-2B	XW2Z-□□□J-B25	
CS1W-NC433	7	NVVZZ-LILIJ-ATT	^	.VV2B-40J0-2B		
CJ1W-NC113		KW2Z-□□□J-A14	×	W2B-20J6-1B		
CJ1W-NC213	,	KW2Z-□□□J-A15		W2B-40J6-2B		
CJ1W-NC413	7	NV2Z	^	WZD-4030-ZD		
CJ1W-NC133		KW2Z-□□□J-A18	×	W2B-20J6-1B		
CJ1W-NC233		KW2Z-□□□J-A19		W2B-40J6-2B		
CJ1W-NC433		NV2Z-000-A19	^	WZD-4030-ZD		
CJ2M-CPU31 CJ2M-CPU32 CJ2M-CPU33 CJ2M-CPU34 CJ2M-CPU35			For 1 axis	XW2B-20J6-8A		
CJ2M-CPU11 CJ2M-CPU12 CJ2M-CPU13 CJ2M-CPU14 CJ2M-CPU15	CJ2M-CPU11 XW2Z-LLLJ-A33 CJ2M-CPU12 CJ2M-CPU13 CJ2M-CPU14		For 2 axis	XW2B-40J6-9A	XW2Z-□□□J-B31	
FQM1-MMP22	General- purpose I/O	ΥΜ27- Ι-Δ28			XW2Z-□□□J-B26	
	Special I/O			MOD 00 17 10 A		
FQM1-MMA22				W2B-80J7-12A –	XW2Z-□□□J-B27	
	Special I/O XW2Z-□□□J-A31					

Note: 1. Insert the cable length into the boxes in the model number ($\square\square$). Position Control Unit cables come in two lengths: 0.5 m and 1 m (some are also available in lengths of 2 m). Servo Driver Cables also come in two lengths: 1 m and 2 m.

- 2. Two Servo Driver Cables are required if 2-axis control is performed using one Position Control Unit.
- 3. Direct cable is available for CJ1W-NC□□4 Position Control Unit (High-Speed type).

Specifications	The number of axes	Model
For CJ1W-NC214/-NC414 (open collector output type)	1 axis	XW2Z-□□□J-G13
For CJ1W-NC214/-NC414 (open collector output type)	2 axis	XW2Z-□□□J-G5
For CJ1W-NC234/-NC434 (line-driver output type)	1 axis	XW2Z-□□□J-G9
For CJ1W-NC234/-NC434 (line-driver output type)	2 axis	XW2Z-□□□J-G1

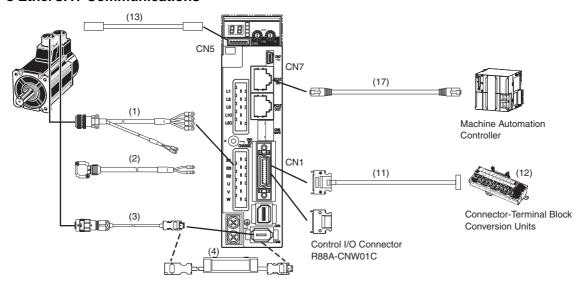
Motion Control Unit Cables

There are special cables for 1-axis and 2-axis Motion Control Unit operation. Select the appropriate cable for the number of axes to be connected.

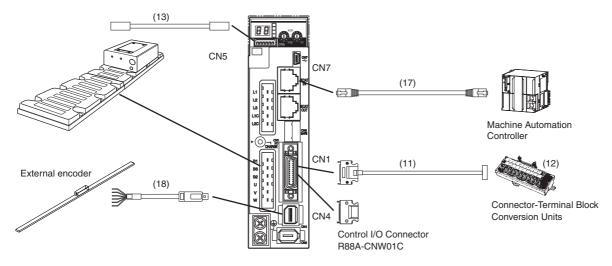
Motion Control Unit	Cable		Remarks	
CS1W-MC221-V1	For 1 axis	R88A-CPG□□□M1	The DDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDDD	
CS1W-MC421-V1	For 2 axis	R88A-CPG□□□M2	Example model number for 2-m 1-axis cable: R88A-CPG002M1	

Cable Combinations

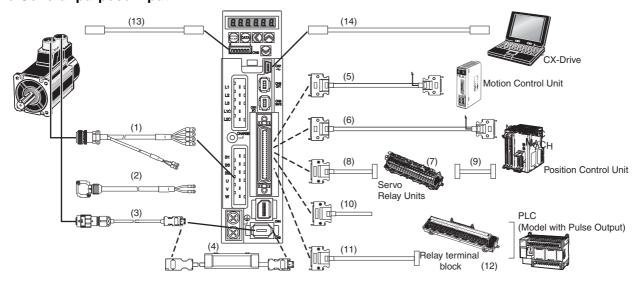
EtherCAT Communications



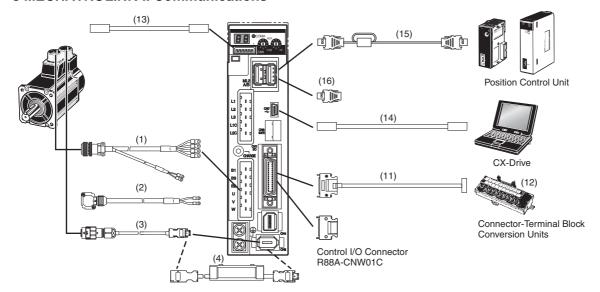
EtherCAT Communications Linear Motor Type



General-purpose Input



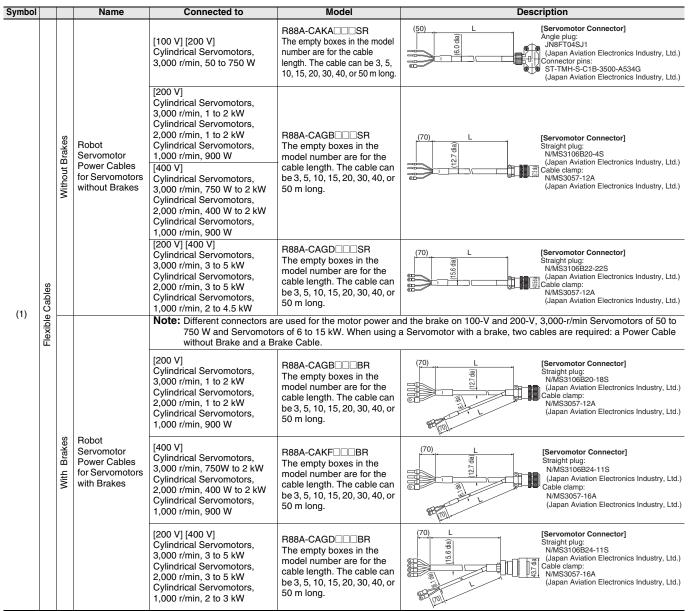
MECHATROLINK-II Communications



AC Servomotor/Drive G5-series

Servomotor Power Cables (For CNB)

Symbol			Name	Connected to	Model	Description		
				[100 V] [200 V] Cylindrical Servomotors, 3,000 r/min, 50 to 750 W	R88A-CAKADDS The empty boxes in the model number are for the cable length. The cable can be 3, 5, 10, 15, 20, 30, 40, or 50 m long.	(50) L [Servomotor Connector] Angle plug: JNBFT045J (Japan Aviation Electronics Industry, Ltd.) ST-TMH-S-C1B-3500-A534G (Japan Aviation Electronics Industry, Ltd.)		
		Without Brakes	Standard Servomotor Power Cables for Servomotors without Brakes	[200 V] Cylindrical Servomotors, 3,000 r/min, 1 to 2 kW Cylindrical Servomotors, 2,000 r/min, 1 to 2 kW Cylindrical Servomotors, 1,000 r/min, 900 W [400 V] Cylindrical Servomotors, 3,000 r/min, 750 W to 2 kW Cylindrical Servomotors, 2,000 r/min, 400 W to 2 kW Cylindrical Servomotors, 1,000 r/min, 900 W	R88A-CAGB S The empty boxes in the model number are for the cable length. The cable can be 3, 5, 10, 15, 20, 30, 40, or 50 m long.	(70) L [Servomotor Connector] Straight plug: N/MS3106B20-4S (Japan Aviation Electronics Industry, Ltd.) Cable clamp: N/MS3057-12A (Japan Aviation Electronics Industry, Ltd.)		
				[200 V] [400 V] Cylindrical Servomotors, 3,000 r/min, 3 to 5 kW Cylindrical Servomotors, 2,000 r/min, 3 to 5 kW Cylindrical Servomotors, 1,000 r/min, 2 to 4.5 kW	R88A-CAGD S The empty boxes in the model number are for the cable length. The cable can be 3, 5, 10, 15, 20, 30, 40, or 50 m long.	(70) L [Servomotor Connector] Straight plug: N/MS3106B22-22S (Japan Aviation Electronics Industry, Ltd.) (Japan Aviation Electronics Industry, Ltd.) (Japan Aviation Electronics Industry, Ltd.)		
(1)	Non-flexible Cables			[200 V] [400 V] Cylindrical Servomotors, 1,500 r/min, 7.5 kW Cylindrical Servomotors, 1,000 r/min, 6 kW	R88A-CAGE□□□S The empty boxes in the model number are for the cable length. The cable can be 3, 5, 10, 15, 20, 30, 40, or 50 m long.	L [Servomotor Connector] Straight plug: N/MS3106B32-17S (Japan Aviation Electronics Industry, Ltd.) M/MS3057-20A (Japan Aviation Electronics Industry, Ltd.)		
	ON	ith Brake			rs of 6 to 15 kW. When using	nd the brake on 100-V and 200-V, 3,000-r/min Servomotors of 50 to a Servomotor with a brake, two cables are required: a Power Cable		
				[200 V] Cylindrical Servomotors, 3,000 r/min, 1 to 2 kW Cylindrical Servomotors, 2,000 r/min, 1 to 2 kW Cylindrical Servomotors, 1,000 r/min, 900 W	R88A-CAGB B The empty boxes in the model number are for the cable length. The cable can be 3, 5, 10, 15, 20, 30, 40, or 50 m long.	(70) L Straight plug: N/MS3106B20-18S (Japan Aviation Electronics Industry, Ltd.) Cable clamp: N/MS3057-12A (Japan Aviation Electronics Industry, Ltd.)		
				[400 V] Cylindrical Servomotors, 3,000 r/min, 750W to 2 kW Cylindrical Servomotors, 2,000 r/min, 400 W to 2 kW Cylindrical Servomotors, 1,000 r/min, 900 W	R88A-CAKF B The empty boxes in the model number are for the cable length. The cable can be 3, 5, 10, 15, 20, 30, 40, or 50 m long.	(70) L [Servomotor Connector] Straight plug: N/MS3106B24-11S (Japan Aviation Electronics Industry, Ltd.) Cable clamp: N/MS3057-16A (Japan Aviation Electronics Industry, Ltd.)		
				[200 V] [400 V] Cylindrical Servomotors, 3,000 r/min, 3 to 5 kW Cylindrical Servomotors, 2,000 r/min, 3 to 5 kW Cylindrical Servomotors, 1,000 r/min, 2 to 3 kW	R88A-CAGD B The empty boxes in the model number are for the cable length. The cable can be 3, 5, 10, 15, 20, 30, 40, or 50 m long.	Straight plug: N/MS3106B24-11S (Japan Aviation Electronics Industry, Ltd.) (Japan Aviation Electronics Industry, Ltd.) (Japan Aviation Electronics Industry, Ltd.)		

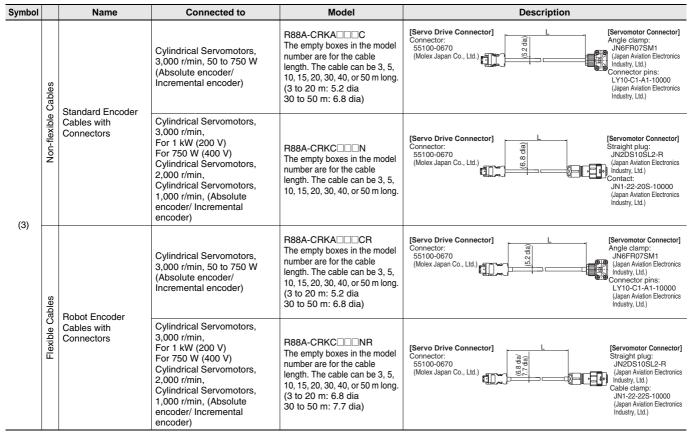


Note: Insert the cable length into the boxes in the model number of cables. (3 m: 003, 5 m: 005, 10 m: 010)

Brake Cables

Symbol		Name	Connected to	Model	Description
	ole Cables	Brake Cables	[100 V] [200 V] Cylindrical Servomotors, 3,000 r/min, 50 to 750 W	R88A-CAKA DB The empty boxes in the model number are for the cable length. The cable can be 3, 5, 10, 15, 20, 30, 40, or 50 m long. (3 to 20 m: 4.4 dia 30 to 50 m: 5.4 dia)	(50) L [Servomotor Connector] Angle plug: JN4FT02SJ1-R (Japan Aviation Electronics Industry, Ltd.) Connector pins: ST-TMH-S-C1B-3500-(A534G) (Japan Aviation Electronics Industry, Ltd.)
(2)	Non-flexible	(Non-flexible Cables)	[200 V] [400 V] Cylindrical Servomotors, 1,500 r/min, 7.5 to 15 kW 1,000 r/min, 6 kW	R88A-CAGE□□□B The empty boxes in the model number are for the cable length. The cable can be 3, 5, 10, 15, 20, 30, 40, or 50 m long. (5.4 dia)	(70) L [Servomotor Connector] Angle plug: N/MS3106B14S-2S (Japan Aviation Electronics Industry, Ltd.) Connector pins: N/MS3057-6A (Japan Aviation Electronics Industry, Ltd.)
	Flexible Cables	Brake Cables (Flexible Cables)	[100 V] [200 V] Cylindrical Servomotors, 3,000 r/min, 50 to 750 W	R88A-CAKA DBR The empty boxes in the model number are for the cable length. The cable can be 3, 5, 10, 15, 20, 30, 40, or 50 m long. (3 to 20 m: 4.4 dia 30 to 50 m: 6.1 dia)	(70) L [Servomotor Connector] Angle plug: JN4FT02SJ1-R (Japan Aviation Electronics Industry, Ltd.) Connector pins: ST-TMH-S-C1B-3500-(A534G) (Japan Aviation Electronics Industry, Ltd.)

Encoder Cables (for CN2)



Note: Insert the cable length into the boxes in the model number of cables. (3 m: 003, 5 m: 005, 10 m: 010)

Absolute Encoder Backup Battery and Absolute Encoder Battery Cable

Symbol	Name	Specifications	Specifications		Description		
		Battery not included	0.3 m	R88A-CRGD0R3C	43.5 300 43.5 90±5 110		
(4)	Absolute Encoder Battery Cable	One R88A-BAT01G Battery included. 0.3 m		R88A-CRGD0R3C-BS			
					t=12 T=27.2 t=12 Battery holder		
	Absolute Encoder Backup Battery			R88A-BAT01G	-		

Control Cables (for CN1)

Symbol	Name	Connected to		Model
(5)	Control Cables for Motion Control Units	Motion Control Units (for all SYSMAC CS1/C200H)	For 1 axis/ For 2 axis	R88A-CPG \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \
	Direct connection cable for Position Control Unit (High-speed type)	Line-driver output type (High-speed type) for CJ1W-NC234/434	For 1 axis	XW2Z-\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\
(6)		Line-driver output type (High-speed type) for CJ1W-NC234/434	For 2 axis	XW2Z-DJ-G1 The empty boxes in the model number are for the cable length. The cable can be 1, 5, or 10 m long.
(6)		Open collector output type (High-speed type) for CJ1W-NC214/NC414	For 1 axis	XW2Z-DDJ-G13 The empty boxes in the model number are for the cable length. The cable can be 1, or 3 m long.
Netel		Open collector output type (High-speed type) for CJ1W-NC214/NC414	For 2 axis	XW2Z-\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\

Symbol		Nai	ne	Connected to		Model
-				Position Control Unit: For CJ1W-NC113/NC133 For CS1W-NC113/NC133 (For C200HW-NC113)	For 1 axis	XW2B-20J6-1B
(7)		Servo Relay Units		Position Control Unit: For CJ1W-NC213/NC233/NC413/NC433 For CS1W-NC213/NC233/NC413/NC433 (For C200HW-NC213/NC413)	For 2 axis	XW2B-40J6-2B
				For CJ1M-CPU21/CPU22/CPU23	For 1 axis	XW2B-20J6-8A
				F01 C31W-CF021/CF022/CF023	For 2 axis	XW2B-40J6-9A
				For FQM1-MMA22 (Analog output) For FQM1-MMP22 (Pulse train output) For 2 axis		XW2B-80J7-12A
				Position Control Unit: For CJ1W-NC□3, CS1W/C200HW-NC□□ (XW2B-20J6-1B, XW2B-40J6-2B)		XW2Z-\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\
(8)		Connection Cables	Servo Relay Unit	For CJ1M-CPU21/CPU22/CPU23 (XW2B-20J6-8A, XW2B-40J6-9A)		XW2Z-□□J-B31 The empty boxes in the model number are for the cable length. The cable can be 1, or 2 m long.
(6)			Servo Drives	For FQM1-MMA22 (Analog output) (XW2B-80J7-12A)		XW2Z-□□□J-B27 The empty boxes in the model number are for the cable length. The cable can be 1, or 2 m long.
	n Cables			For FQM1-MMP22 (Pulse train output) (XW2B-80J7-12A)		XW2Z-□□□J-B26 The empty boxes in the model number are for the cable length. The cable can be 1, or 2 m long.
	/Connection		Servo Relay Unit Cables for Position Control Units	CJ1W line-driver output type for CJ1W-NC133	For 1 axis	XW2Z-_\J-A18 The empty boxes in the model number are for the cable length. The cable can be 0.5, or 1 m long.
	Servo Relay Units/Connection Cables			CJ1W line-driver output type for CJ1W-NC233/NC433	For 2 axis	XW2Z-\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\
				CS1W line-driver output type for CS1W-NC133	For 1 axis	XW2Z-_\J-A10 The empty boxes in the model number are for the cable length. The cable can be 0.5, or 1 m long.
				CS1W line-driver output type for CS1W-NC233/NC433	For 2 axis	XW2Z-□□J-A11 The empty boxes in the model number are for the cable length. The cable can be 0.5, or 1 m long.
(9)				CJ1W open collector output type for CJ1W-NC113	For 1 axis	XW2Z-□□J-A14 The empty boxes in the model number are for the cable length. The cable can be 0.5, or 1 m long.
				CJ1W open collector output type for CJ1W-NC213/NC413	For 2 axis	XW2Z-□□J-A15 The empty boxes in the model number are for the cable length. The cable can be 0.5, or 1 m long.
				CS1W/C200HW open collector output type for CS1W-NC113 for C200HW-NC113	For 1 axis	XW2Z-□□□J-A6 The empty boxes in the model number are for the cable length. The cable can be 0.5, or 1 m long.
				CS1W/C200HW open collector output type for CS1W-NC213/NC413 for C200HW-NC213/NC413	For 2 axis	XW2Z-□□□J-A7 The empty boxes in the model number are for the cable length. The cable can be 0.5, or 1 m long.
				CSW/C200HW open collector output type for CJ2M-CPU31/CPU32/CPU33/CPU34/CPU35 for CJ2M-CPU11/CPU12/CPU13/CPU14/CPU15	For 1 axis	XW2Z-\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\

AC Servomotor/Drive G5-series

Symbol		Nar	ne		Connected to		Model
	on Cables			For FQM1-MMA22 (Analog output) For FQM1-MMP22 (Pulse train output)	General-purpose I/O (26 pin)	For 2 axis	XW2Z-□□□J-A28 The empty boxes in the model number are for the cable length. The cable can be 0.5, 1, or 2 m long.
(9)	Units/Connection	Connection Cables	Servo Relay Unit Cables for Position Control Units	For FQM1-MMA22 (Analog output)	Special I/O (40 pin)	For 2 axis	XW2Z-□□□J-A31 The empty boxes in the model number are for the cable length. The cable can be 0.5, 1, or 2 m long.
	Servo Relay Un			For FQM1-MMP22 (Pulse train output)	Special I/O (40 pin)	For 2 axis	XW2Z-_\J-A30 The empty boxes in the model number are for the cable length. The cable can be 0.5, 1, or 2 m long.
(10)		neral-purpose Control (n Connector on One En		Cables for General-purpose Controllers			R88A-CPG□□S The empty boxes in the model number are for the cable length. The cable can be 0.5, or 1 m long.
(44)		Connector		Cable for General-purpose Controllers			XW2Z-□□□J-B24 The empty boxes in the model number are for the cable length. The cable can be 1, or 2 m long.
(11)	Terminal Block Cables For Connector Terminal			Cable for MECHATROLINK-II Communications			XW2Z-□□□J-B34 The empty boxes in the model number are for the cable length. The cable can be 1, or 2 m long.
	Blo	ck				M3 screws	XW2B-50G4
				Cable for General-purpo	ose Controllers	M3.5 screws	XW2B-50G5
(12)			Connector- Terminal Block			M3 screws	XW2D-50G6
(12)		Conversion Ur				M3 screws	XW2B-20G4
				Cable for MECHATROLINK-II Communications		M3.5 screws	XW2B-20G5
					M3 screws	XW2D-20G6	

Note: Insert the cable length into the boxes in the model number of cables. (3 m: 003, 5 m: 005, 10 m: 010)

Monitor Connector (for CN5)

Symbol	Name	Lengths	Model	
(13)	Analog Monitor Cable	1 m	R88A-CMK001S	

Communications Connector (for CN7)

Symbol	Name	Description
(14)	USB communications cable	General purpose USB cable can be used

Note: Use a commercially available USB cable that is shield, equipped with a ferrite core for noise immunity, and Supporting for USB2.0. The Mini B type USB cable can be used.

MECHATROLINK-II Communication Cable

Symbol	Name	Length (L)	Model (OMRON model number)	Yaskawa model number	Description	
	MECHATROLINK-II	0.5m	FNY-W6002-A5	JEPMC-W6002-A5-E	(without ring core and USB connector on both ends)	
	Communication Cable	1m	FNY-W6002-01	JEPMC-W6002-01-E	(without fing core and odd connector on both ends)	
	* Can be connected to R88D-GN and	3m	FNY-W6002-03	JEPMC-W6002-03-E		
	R88D-KN only.	5m	FNY-W6002-05	JEPMC-W6002-05-E		
		0.5m	FNY-W6003-A5	JEPMC-W6003-A5		
(15)	MECHATROLINK-II Communication Cable	1m	FNY-W6003-01	JEPMC-W6003-01		
		Communication	3m	FNY-W6003-03	JEPMC-W6003-03	(with ring core and USB connector on both ends)
			5m	FNY-W6003-05	JEPMC-W6003-05	L
		10m	FNY-W6003-10	JEPMC-W6003-10		
		20m	FNY-W6003-20	JEPMC-W6003-20	Core	
		30m	FNY-W6003-30	JEPMC-W6003-30		
(16)	MECHATROLINK-II Terminating resistance	-	FNY-W6022	JEPMC-W6022	12 46 (8)	

EtherCAT Communication Cable

Symbol	Name	Description
(17)	Ethernet Cable	EtherCAT Communication Cables Use a category 5 or higher cable with double, aluminum tape and braided shielding. Connector (Modular Plug) Specifications Use a category 5 or higher, shielded connector.

External encoder Cables

Symbol	Name	Length (L)	Model	Description
(18)	Serial Communications Cable	10m	R88A-CRKE010SR	CN4 with Connectors

Connectors

Connectors	Name	Model
	Control I/O Connector (General-purpose Input)	R88A-CNU11C
CN1	Control I/O Connector (MECHATROLINK-II Communications) (EtherCAT Communications)	R88A-CNW01C
CN2	Encoder Connector	R88A-CNW01R
CN4	External scale connector	R88A-CNK41L
CN8	Safety connector	R88A-CNK81S

Servomotor Connector

Connectors	Name	Connected to	Model
-	Motor connector for encoder cable	3,000 r/min, 50 to 750 W	R88A-CNK02R
		3,000 r/min, 1 to 5 kW (200 V)/750 W to 5 kW (400 V) 2,000 r/min, 1,000 r/min	R88A-CNK04R
_	Power cable connector	750 W max. (100 V/200 V)	R88A-CNK11A
_	Brake cable connector	750 W max. (100 V/200 V)	R88A-CNK11B

Related Manuals

Please read the relevant manuals of G5-Series

English Cat. No.	Japanese Cat. No.	Туре	Name
1571	SBCE-357	R88D-KT/R88M-K	G5-SERIES AC SERVOMOTOR AND SERVO DRIVE USER'S MANUAL
1572	SBCE-358	R88D-KN□-ML2/R88M-K	G5-SERIES MECHATROLINK-II Communications AC SERVOMOTOR AND SERVO DRIVE USER'S MANUAL
1573	SBCE-360	R88D-KN□-ECT-R/R88M-K	G5-SERIES EtherCAT Communications for Position Control AC SERVOMOTOR AND SERVO DRIVE USER'S MANUAL
1576	SBCE-365	R88D-KN□-ECT/R88M-K	G5-SERIES EtherCAT Communications AC SERVOMOTOR AND SERVO DRIVE USER'S MANUAL
1577	SBCE-366	R88D-KN□-ECT-L/R88L-EC	G5-SERIES EtherCAT Communications Linear Motor Type LINEARMOTOR AND DRIVE USER'S MANUAL
W487	SBCE-359	CJ1W-NC□81/CJ1W-NC□82	CJ-series Position Control Unit Operation Manual
W446	SBCA-337	CXONE-AL C-V-AL D-V	CX-Programmer Operation Manual
W453	SBCE-375	CXONE-UUUC-VU/UUUD-VU	CX-Drive OPERATION MANUAL
W504	SBCA-362	SYSMAC-SE2□□□	Sysmac Studio Version 1 Operation Manual

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Related product catalog



Programmable Controller SYSMAC CJ Series Position Control Units (High-Speed type)

CJ1W-NC214/414 CJ1W-NC234/434

Cat. No. R156



AC Servomotors/ Servo Drives

G Series

Cat. No. 1814



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